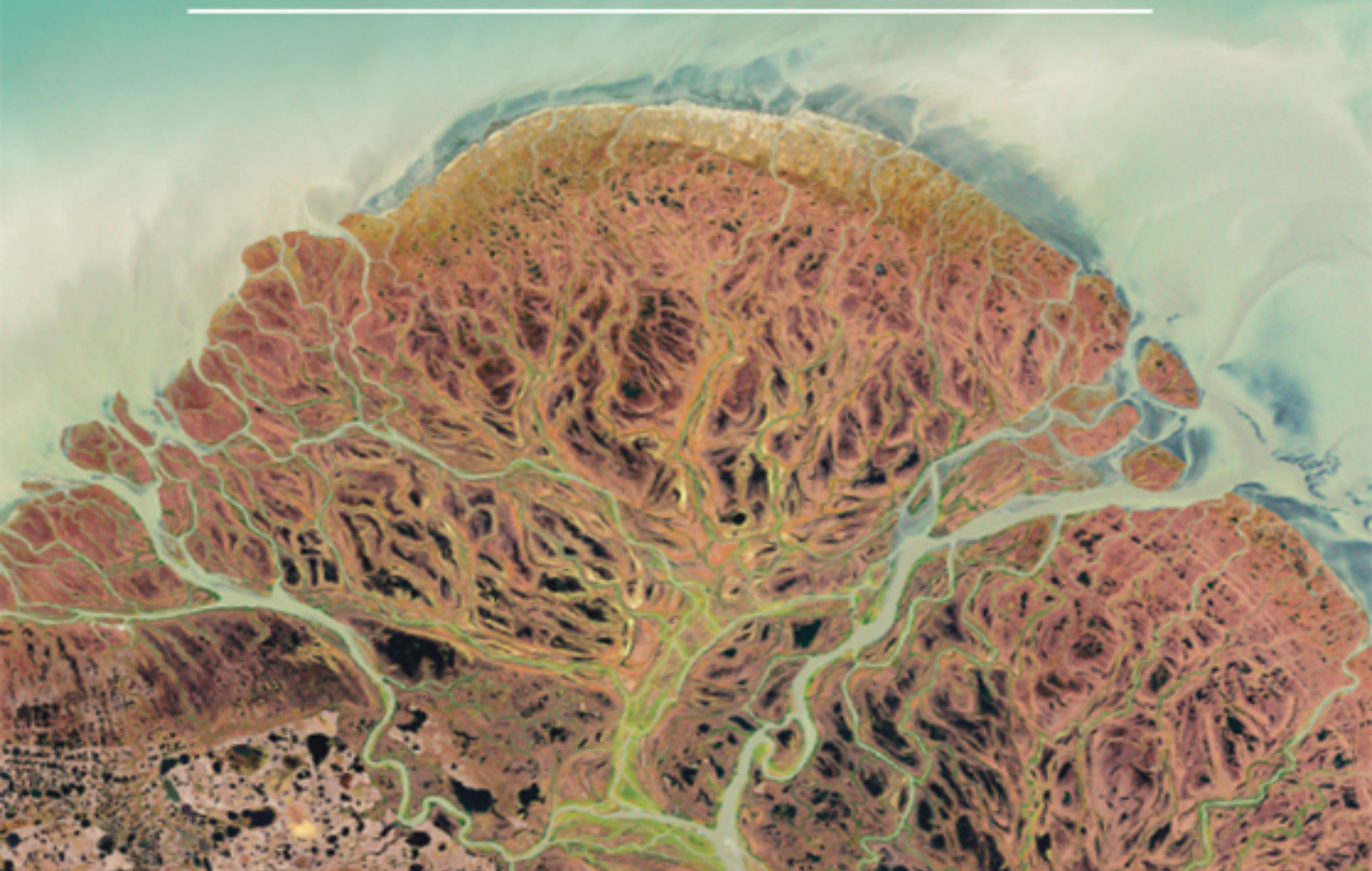


# MULTIPLE-POINT GEOSTATISTICS

Stochastic Modeling with Training Images

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**Gregoire Mariethoz • Jef Caers**



**WILEY** Blackwell

# Multiple-point geostatistics

## Stochastic modeling with training images

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Figure II.6.9 (a-c) Reference (identical to Figure II.6.2), shown here for comparison. (d-f) One multivariate conditional realization obtained using direct sampling. (g-i) The average of 10 conditional realizations.

Figure II.6.10 (a-c) Scatterplot of all co-located values in one realization. Lower half of the figure: conditional histograms to better illustrate the relationship with binary variable 3.

Figure II.6.11 3D scatterplot of all three variables in the realization.

Figure II.6.12 Illustration of the image analogy notation with a by-example filtering application. Modified from Hertzmann, A., C. E. Jacobs, et al. (2001).

Figure II.6.13 Identification of geological structures from a georadar survey. A and A': training image (Bayer et al., 2011). B': another georadar survey taken in a similar geological environment. B:

simulated photograph honoring the relationship B : B'.

Figure II.6.14 Scatterplots of (a) the multivariate training images and (b) multivariate realization of Figure II.6.13.

## Chapter 13

Figure II.7.1 A simple object-based model of channelized structures. Image obtained with the TiGenerator software (Maharaja, 2008). Grid size: 250×250×100 nodes.

Figure II.7.2 An object-based model considering variable channel width and depth, randomized sinuosity, and different facies for the various architectural elements (main channel and levees). Image obtained with the FLUVSIM software (Deutsch and Tran, 2002). Grid size: 250×250×100 nodes.

Figure II.7.3 Process-based reconstruction of the Alameda Creek alluvial fan. Reprinted from Paleoclimatic signature in terrestrial flood deposits. Science 256(5065): 1775–1782. With permission from AAAS.

Figure II.7.4 (a) Process-based modeling from tank experiments (data courtesy of Saint Anthony Falls Laboratory, University of Minnesota). (b) Interpretation from the overhead photos (data courtesy of Siyao Xu).

Figure II.7.5 A process-mimicking model of an alluvial reservoir using the FLUMY simulation method (Lopez et al., 2008). The spatial organization of the structural elements is based on physical equations. Grid size: 500×500×200 nodes.

Figure II.7.6 Process-based (data courtesy of Exxon) versus process-mimicking models (Michael et al., 2010).

Figure II.7.7 Left: elementary training image (size: 50×50×50 nodes). Right: one realization using rotation-invariant distances (size: 180×150×120 nodes). Rotation-invariant distances are considering angles of +/− 90° in all directions.

Figure II.7.8 Left: elementary training image (size: 50×50×50 nodes). Right: one realization using rotation-invariant distances (size: 180×150×120 nodes). Rotation-invariant distances are considering angles of +/− 20° in all directions.

Figure II.7.9 Merging of compatible orthogonal data events. Modified/Reprinted from Comunian, A., P. Renard, et al. (2012). With permission from Elsevier.

Figure II.7.10 Method of perpendicular sections. (a) Orthogonal training images. (b) The first sections simulated are those that intersect at the location of conditioning data (wells). (c) The remaining sections are generated sequentially until (d) the entire 3D volume is simulated (modified from Kessler et al., 2013).

Figure II.7.11 Reconstruction of a partial image based on the principle of training data. (a) Infrared satellite data of the Pacific Ocean presenting gaps (source: National Oceanic and Atmospheric Administration (NOAA)). (b) One reconstruction simulation based on (a); here, the data are used as both training data and conditioning data. Dark blue represents gaps, and darker blue represents continents.

Figure II.7.12 (a) Lithological facies. (b) Sediment grain size. (c) Sediment age since the time of deposition.

Figure II.7.13 A multivariate training image made of (a) a hydraulic conductivity field; and (b-f) snapshots of contaminant distribution at different time stamps.

## Chapter 14

Figure II.8.1 Illustration case involving as data: one well, three possible training images, and two possible trend models.

Figure II.8.2 (a) Single synthetic well datum; (b) another synthetic well datum; (c) smoothing of the first well datum; (d) smoothing of the second well datum; (e) MDS plot based on the Euclidean distance between the smoothed data; and (f) MDS plot based on the Jensen-Shannon distance of the MPHs for each well datum. Black crosses are the field well data.

Figure II.8.3 Illustration of the concept of connected components based on the Tropical Rainfall Measuring Mission (TRMM) data, shown in (a). The continuous variable representing accumulated rainfall in (b) is converted to the binary variable (c) on which a connected component analysis is applied (d); 1793 connected components are found for the category corresponding to rainfall  $>1$  mm/12 hours.

Figure II.8.4 Illustration of the connectivity function based on the connected component analysis of Figure II.8.3.

Figure II.8.5 Illustration of coherence maps for three test cases. All cases are unconditional DS realizations, with fraction of training image,  $f = 1$ , threshold  $t = 0$ . (a) A categorical variable with  $n = 40$

neighbor nodes. (b) A continuous variable with  $n = 20$  neighbor nodes. (c) The same continuous variable with  $n = 60$  neighbor nodes. The color codes in the coherence maps represent the IDs of the nodes in the training image.

Figure II.8.6 Illustration of multiscale pyramids of a single model.

Figure II.8.7 Case with a two wells (a) and simple binary 3D stationary training image (b). Realization of both CCSIM (c) and SNESIM (d) from a set of 50 realizations with each method.

Figure II.8.8 Top: local ANODI. Bottom: MDS plot from global ANODI.

Figure II.8.9 Ensemble average for 50 CCSIM realizations; and 50 SNESIM realizations.

## Chapter 15

Figure II.9.1 A Gaussian prior and a simple tracer problem. A tracer is injected at the left location, and its arrival monitored at the right location. Various Gaussian models are sampled from which the tracer response is calculated.

Figure II.9.2 Studying the convergence of the gradual deformation when changing the concentration curves to earlier and later breakthrough times.

Figure II.9.3 An example of a new MPS realization generated with SNESIM (c), based on an existing one (a), using a spatial resampling of data points as well as constrained to existing conditioning data at four well locations (b). (d) Training image. The realization grid is of dimension  $100 \times 100 \times 40$ , and the training image of dimension  $150 \times 200 \times 80$ .