

MAGNETIC  
RESONANCE  
IMAGING



*Physical Principles  
and Sequence Design*

*Second Edition*

ROBERT W. BROWN, PH.D.

YU-CHUNG N. CHENG, PH.D.

E. MARK HAACKE, PH.D.

MICHAEL R. THOMPSON, PH.D.

RAMESH VENKATESAN, D.Sc.

**WILEY** Blackwell



# Magnetic Resonance Imaging: Physical Principles and Sequence Design

Second Edition

Robert W. Brown, Ph.D.

*Institute Professor and Distinguished University Professor  
Case Western Reserve University, Cleveland, Ohio, USA*

Yu-Chung N. Cheng, Ph.D.

*Associate Professor of Radiology  
Wayne State University, Detroit, Michigan, USA*

E. Mark Haacke, Ph.D.

*Professor of Radiology, Wayne State University, Detroit, Michigan, USA  
Professor of Physics, Case Western Reserve University, Cleveland, Ohio, USA  
Adjunct Professor of Radiology, Loma Linda University, Loma Linda, California, USA  
Adjunct Professor of Radiology, McMaster University, Hamilton, Ontario, Canada  
Distinguished Foreign Professor, Northeastern University, Shenyang, Liaoning, China*

Michael R. Thompson, Ph.D.

*Principal Scientist, Toshiba Medical Research Institute,  
Cleveland, Ohio, USA*

Ramesh Venkatesan, D.Sc.

*Principal Engineer, MR Software & Applications Engineering  
Wipro GE Healthcare Pvt. Ltd., Bangalore, India*

**WILEY Blackwell**

This edition copyright © 2014 by John Wiley & Sons, Inc. All rights reserved.  
First edition copyright © 1999 by John Wiley & Sons, Inc. All rights reserved.

Published by John Wiley & Sons, Inc., Hoboken, New Jersey  
Published simultaneously in Canada

No part of this publication may be reproduced, stored in a retrieval system, or transmitted in any form or by any means, electronic, mechanical, photocopying, recording, scanning, or otherwise, except as permitted under Section 107 or 108 of the 1976 United States Copyright Act, without either the prior written permission of the Publisher, or authorization through payment of the appropriate per-copy fee to the Copyright Clearance Center, Inc., 222 Rosewood Drive, Danvers, MA 01923, (978) 750-8400, fax (978) 750-4470, or on the web at [www.copyright.com](http://www.copyright.com). Requests to the Publisher for permission should be addressed to the Permissions Department, John Wiley & Sons, Inc., 111 River Street, Hoboken, NJ 07030, (201) 748-6011, fax (201) 748-6008, or online at <http://www.wiley.com/go/permission>.

The contents of this work are intended to further general scientific research, understanding, and discussion only and are not intended and should not be relied upon as recommending or promoting a specific method, diagnosis, or treatment by health science practitioners for any particular patient. The publisher and the author make no representations or warranties with respect to the accuracy or completeness of the contents of this work and specifically disclaim all warranties, including without limitation any implied warranties of fitness for a particular purpose. In view of ongoing research, equipment modifications, changes in governmental regulations, and the constant flow of information relating to the use of medicines, equipment, and devices, the reader is urged to review and evaluate the information provided in the package insert or instructions for each medicine, equipment, or device for, among other things, any changes in the instructions or indication of usage and for added warnings and precautions. Readers should consult with a specialist where appropriate. The fact that an organization or Website is referred to in this work as a citation and/or a potential source of further information does not mean that the author or the publisher endorses the information the organization or Website may provide or recommendations it may make. Further, readers should be aware that Internet Websites listed in this work may have changed or disappeared between when this work was written and when it is read. No warranty may be created or extended by any promotional statements for this work. Neither the publisher nor the author shall be liable for any damages arising herefrom.

For general information on our other products and services or for technical support, please contact our Customer Care Department within the United States at (800) 762-2974, outside the United States at (317) 572-3993 or fax (317) 572-4002.

Wiley also publishes its books in a variety of electronic formats. Some content that appears in print may not be available in electronic formats. For more information about Wiley products, visit our website at [www.wiley.com](http://www.wiley.com).

*Library of Congress Cataloging-in-Publication Data*

Brown, Robert W., 1941– author.

Magnetic resonance imaging : physical principles and sequence design / Robert W. Brown, Yu-Chung N. Cheng, E. Mark Haacke, Michael R. Thompson, Ramesh Venkatesan. – Second edition. p. ; cm.

Preceded by Magnetic resonance imaging : physical principles and sequence design / E. Mark Haacke ... [et al.]. c1999.

Includes bibliographical references and index.

ISBN 978-0-471-72085-0 (cloth)

I. Cheng, Yu-Chung N., author. II. Haacke, E. Mark., author. III. Thompson, Michael R., author. IV. Venkatesan, Ramesh., author. V. Title.

[DNLM: 1. Magnetic Resonance Imaging. 2. Physical Phenomena. WN 185]

RC78.7.N83

616.07'548–dc23

2014000051

Cover design by Wiley

Printed in

10 9 8 7 6 5 4 3 2 1

# Contents

<b>Foreword to the Second Edition</b>	<b>xvii</b>
<b>Foreword to the First Edition</b>	<b>xxi</b>
<b>Preface to the Second Edition</b>	<b>xxvii</b>
<b>Preface to the First Edition</b>	<b>xxx</b>
<b>Acknowledgements</b>	<b>xxx</b>
<b>Acknowledgements to the First Edition</b>	<b>xxxii</b>
<b>1 Magnetic Resonance Imaging: A Preview</b>	<b>1</b>
1.1 Magnetic Resonance Imaging: The Name . . . . .	1
1.2 The Origin of Magnetic Resonance Imaging . . . . .	2
1.3 A Brief Overview of MRI Concepts . . . . .	3
1.3.1 Fundamental Interaction of a Proton Spin with the Magnetic Field . . . . .	3
1.3.2 Equilibrium Alignment of Spin . . . . .	4
1.3.3 Detecting the Magnetization of the System . . . . .	5
1.3.4 Magnetic Resonance Spectroscopy . . . . .	7
1.3.5 Magnetic Resonance Imaging . . . . .	7
1.3.6 Relaxation Times . . . . .	8
1.3.7 Resolution and Contrast . . . . .	9
1.3.8 Magnetic Field Strength . . . . .	10
1.3.9 Key Developments in Magnetic Resonance . . . . .	12
<b>2 Classical Response of a Single Nucleus to a Magnetic Field</b>	<b>19</b>
2.1 Magnetic Moment in the Presence of a Magnetic Field . . . . .	20
2.1.1 Torque on a Current Loop in a Magnetic Field . . . . .	20
2.1.2 Magnet Toy Model . . . . .	24
2.2 Magnetic Moment with Spin: Equation of Motion . . . . .	25
2.2.1 Torque and Angular Momentum . . . . .	25
2.2.2 Angular Momentum of the Proton . . . . .	26
2.2.3 Electrons and Other Elements . . . . .	27
2.2.4 Equation of Motion . . . . .	28
2.3 Precession Solution: Phase . . . . .	29
2.3.1 Precession via the Gyroscope Analogy . . . . .	29
2.3.2 Geometrical Representation . . . . .	31
2.3.3 Cartesian Representation . . . . .	32

2.3.4	Matrix Representation . . . . .	34
2.3.5	Complex Representations and Phase . . . . .	34
<b>3</b>	<b>Rotating Reference Frames and Resonance</b>	<b>37</b>
3.1	Rotating Reference Frames . . . . .	38
3.2	The Rotating Frame for an RF Field . . . . .	41
3.2.1	Polarization . . . . .	42
3.2.2	Quadrature . . . . .	43
3.3	Resonance Condition and the RF Pulse . . . . .	44
3.3.1	Flip-Angle Formula and Illustration . . . . .	45
3.3.2	RF Solutions . . . . .	46
3.3.3	Different Polarization Bases . . . . .	47
3.3.4	Laboratory Angle of Precession . . . . .	49
<b>4</b>	<b>Magnetization, Relaxation, and the Bloch Equation</b>	<b>53</b>
4.1	Magnetization Vector . . . . .	53
4.2	Spin-Lattice Interaction and Regrowth Solution . . . . .	54
4.3	Spin-Spin Interaction and Transverse Decay . . . . .	57
4.4	Bloch Equation and Static-Field Solutions . . . . .	60
4.5	The Combination of Static and RF Fields . . . . .	62
4.5.1	Bloch Equation for $\vec{B}_{ext} = B_0\hat{z} + B_1\hat{x}'$ . . . . .	62
4.5.2	Short-Lived RF Pulses . . . . .	63
4.5.3	Long-Lived RF Pulses . . . . .	64
<b>5</b>	<b>The Quantum Mechanical Basis of Precession and Excitation</b>	<b>67</b>
5.1	Discrete Angular Momentum and Energy . . . . .	68
5.2	Quantum Operators and the Schrödinger Equation . . . . .	72
5.2.1	Wave Functions . . . . .	73
5.2.2	Momentum and Angular Momentum Operators . . . . .	74
5.2.3	Spin Solutions for Constant Fields . . . . .	76
5.3	Quantum Derivation of Precession . . . . .	77
5.4	Quantum Derivation of RF Spin Tipping . . . . .	80
<b>6</b>	<b>The Quantum Mechanical Basis of Thermal Equilibrium and Longitudinal Relaxation</b>	<b>85</b>
6.1	Boltzmann Equilibrium Values . . . . .	86
6.2	Quantum Basis of Longitudinal Relaxation . . . . .	89
6.3	The RF Field . . . . .	92
<b>7</b>	<b>Signal Detection Concepts</b>	<b>95</b>
7.1	Faraday Induction . . . . .	96
7.2	The MRI Signal and the Principle of Reciprocity . . . . .	99
7.3	Signal from Precessing Magnetization . . . . .	101

7.3.1	General Expression . . . . .	101
7.3.2	Spatial Independence . . . . .	103
7.3.3	Signal Demodulation . . . . .	104
7.3.4	Dependent Channels and Independent Coils . . . . .	107
7.4	Dependence on System Parameters . . . . .	107
7.4.1	Homogeneous Limit . . . . .	107
7.4.2	Relative Signal Strength . . . . .	108
7.4.3	Radiofrequency Field Effects . . . . .	110
<b>8</b>	<b>Introductory Signal Acquisition Methods: Free Induction Decay, Spin Echoes, Inversion Recovery, and Spectroscopy</b>	<b>113</b>
8.1	Free Induction Decay and $T_2^*$ . . . . .	114
8.1.1	FID Signal . . . . .	114
8.1.2	Phase Behavior and Phase Conventions . . . . .	115
8.1.3	$T_2^*$ Decay . . . . .	117
8.1.4	The FID Sequence Diagram and Sampling . . . . .	119
8.2	The Spin Echo and $T_2$ Measurements . . . . .	120
8.2.1	The Spin Echo Method . . . . .	120
8.2.2	Spin Echo Envelopes . . . . .	123
8.2.3	Limitations of the Spin Echo . . . . .	124
8.2.4	Spin Echo Sampling . . . . .	125
8.2.5	Multiple Spin Echo Experiments . . . . .	125
8.3	Repeated RF Pulse Structures . . . . .	126
8.3.1	The FID Signal from Repeated RF Pulse Structures . . . . .	127
8.3.2	The Spin Echo Signal from Repeated RF Pulse Structures . . . . .	129
8.4	Inversion Recovery and $T_1$ Measurements . . . . .	131
8.4.1	$T_1$ Measurement . . . . .	132
8.4.2	Repeated Inversion Recovery . . . . .	134
8.5	Spectroscopy and Chemical Shift . . . . .	136
<b>9</b>	<b>One-Dimensional Fourier Imaging, <math>k</math>-Space, and Gradient Echoes</b>	<b>141</b>
9.1	Signal and Effective Spin Density . . . . .	142
9.1.1	Complex Demodulated Signal . . . . .	142
9.1.2	Magnetization and Effective Spin Density . . . . .	143
9.2	Frequency Encoding and the Fourier Transform . . . . .	144
9.2.1	Frequency Encoding of the Spin Position . . . . .	144
9.2.2	The 1D Imaging Equation and the Fourier Transform . . . . .	145
9.2.3	The Coverage of $k$ -Space . . . . .	146
9.2.4	Rect and Sinc Functions . . . . .	147
9.3	Simple Two-Spin Example . . . . .	147
9.3.1	Dirac Delta Function . . . . .	150
9.3.2	Imaging Sequence Diagrams Revisited . . . . .	151
9.4	Gradient Echo and $k$ -Space Diagrams . . . . .	151
9.4.1	The Gradient Echo . . . . .	153
9.4.2	General Spin Echo Imaging . . . . .	156

9.4.3	Image Profiles . . . . .	158
9.5	Gradient Directionality and Nonlinearity . . . . .	162
9.5.1	Frequency Encoding in an Arbitrary Direction . . . . .	162
9.5.2	Nonlinear Gradients . . . . .	163
<b>10</b>	<b>Multi-Dimensional Fourier Imaging and Slice Excitation</b>	<b>165</b>
10.1	Imaging in More Dimensions . . . . .	166
10.1.1	The Imaging Equation . . . . .	166
10.1.2	Single Excitation Traversal of $k$ -Space . . . . .	169
10.1.3	Time Constraints and Collecting Data over Multiple Cycles . . . . .	171
10.1.4	Variations in $k$ -Space Coverage . . . . .	174
10.2	Slice Selection with Boxcar Excitations . . . . .	175
10.2.1	Slice Selection . . . . .	175
10.2.2	Gradient Rephasing After Slice Selection . . . . .	178
10.2.3	Arbitrary Slice Orientation . . . . .	180
10.3	2D Imaging and $k$ -Space . . . . .	184
10.3.1	Gradient Echo Example . . . . .	184
10.3.2	Spin Echo Example . . . . .	193
10.4	3D Volume Imaging . . . . .	194
10.4.1	Short- $T_R$ 3D Gradient Echo Imaging . . . . .	194
10.4.2	Multi-Slice 2D Imaging . . . . .	195
10.5	Chemical Shift Imaging . . . . .	197
10.5.1	A 2D-Spatial 1D-Spectral Method . . . . .	200
10.5.2	A 3D-Spatial, 1D-Spectral Method . . . . .	204
<b>11</b>	<b>The Continuous and Discrete Fourier Transforms</b>	<b>207</b>
11.1	The Continuous Fourier Transform . . . . .	208
11.2	Continuous Transform Properties and Phase Imaging . . . . .	209
11.2.1	Complexity of the Reconstructed Image . . . . .	211
11.2.2	The Shift Theorem . . . . .	211
11.2.3	Phase Imaging and Phase Aliasing . . . . .	212
11.2.4	Duality . . . . .	215
11.2.5	Convolution Theorem . . . . .	215
11.2.6	Convolution Associativity . . . . .	218
11.2.7	Derivative Theorem . . . . .	219
11.2.8	Fourier Transform Symmetries . . . . .	220
11.2.9	Summary of Continuous Fourier Transform Properties . . . . .	220
11.3	Fourier Transform Pairs . . . . .	220
11.3.1	Heaviside Function . . . . .	222
11.3.2	Lorentzian Form . . . . .	222
11.3.3	The Sampling Function . . . . .	223
11.4	The Discrete Fourier Transform . . . . .	223
11.5	Discrete Transform Properties . . . . .	225
11.5.1	The Discrete Convolution Theorem . . . . .	226
11.5.2	Summary of Discrete Fourier Transform Properties . . . . .	227



<b>12 Sampling and Aliasing in Image Reconstruction</b>	<b>229</b>
12.1 Infinite Sampling, Aliasing, and the Nyquist Criterion . . . . .	230
12.1.1 Infinite Sampling . . . . .	230
12.1.2 Nyquist Sampling Criterion . . . . .	232
12.2 Finite Sampling, Image Reconstruction, and the Discrete Fourier Transform .	237
12.2.1 Finite Sampling . . . . .	237
12.2.2 Reconstructed Spin Density . . . . .	239
12.2.3 Discrete and Truncated Sampling of $\hat{\rho}(x)$ : Resolution . . . . .	240
12.2.4 Discrete Fourier Transform . . . . .	242
12.2.5 Practical Parameters . . . . .	244
12.3 RF Coils, Noise, and Filtering . . . . .	245
12.3.1 RF Field-of-View Considerations . . . . .	245
12.3.2 Analog Filtering . . . . .	245
12.3.3 Avoiding Aliasing in 3D Imaging . . . . .	250
12.4 Nonuniform Sampling . . . . .	250
12.4.1 Aliasing from Interleaved Sampling . . . . .	250
12.4.2 Aliasing from Digital-to-Analog Error in the Gradient Specification .	258
<b>13 Filtering and Resolution in Fourier Transform Image Reconstruction</b>	<b>261</b>
13.1 Review of Fourier Transform Image Reconstruction . . . . .	262
13.1.1 Fourier Encoding and Fourier Inversion . . . . .	262
13.1.2 Infinite Sampling and Fourier Series . . . . .	263
13.1.3 Limited-Fourier Imaging and Aliasing . . . . .	263
13.1.4 Signal Series and Spatial Resolution . . . . .	264
13.2 Filters and Point Spread Functions . . . . .	264
13.2.1 Point Spread Due to Truncation . . . . .	265
13.2.2 Point Spread for Truncated and Sampled Data . . . . .	266
13.2.3 Point Spread for Additional Filters . . . . .	267
13.3 Gibbs Ringing . . . . .	267
13.3.1 Gibbs Overshoot and Undershoot . . . . .	267
13.3.2 Gibbs Oscillation Frequency . . . . .	269
13.3.3 Reducing Gibbs Ringing by Filtering . . . . .	270
13.4 Spatial Resolution in MRI . . . . .	272
13.4.1 Resolution after Additional Filtering of the Data . . . . .	277
13.4.2 Other Measures of Resolution . . . . .	278
13.5 Hanning Filter and $T_2^*$ Decay Effects . . . . .	281
13.5.1 Resolution Due to the Hanning Filter . . . . .	281
13.5.2 Partial Fourier $T_2^*$ Reconstruction Effects . . . . .	281
13.6 Zero Filled Interpolation, Sub-Voxel Fourier Transform Shift Concepts, and Point Spread Function Effects . . . . .	283
13.6.1 Zero Padding and the Fast Fourier Transform . . . . .	283
13.6.2 Equivalence of Zero Filled Image and the Sub-Voxel Shifted Image .	284

13.6.3	Point Spread Effects on the Image Based on the Object Position Relative to the Reconstructed Voxels . . . . .	285
13.7	Partial Fourier Imaging and Reconstruction . . . . .	286
13.7.1	Forcing Conjugate Symmetry on Complex Objects . . . . .	290
13.7.2	Iterative Reconstruction . . . . .	290
13.7.3	Some Implementation Issues . . . . .	292
13.8	Digital Truncation . . . . .	293
<b>14</b>	<b>Projection Reconstruction of Images</b>	<b>297</b>
14.1	Radial $k$ -Space Coverage . . . . .	298
14.1.1	Coverage of $k$ -Space at Different Angles . . . . .	299
14.1.2	Two Radial Fourier Transform Examples . . . . .	300
14.1.3	Inversion for Image Reconstruction . . . . .	301
14.2	Sampling Radial $k$ -Space and Nyquist Limits . . . . .	302
14.3	Projections and the Radon Transform . . . . .	308
14.4	Methods of Projection Reconstruction with Radial Coverage . . . . .	310
14.4.1	X-Ray Analog . . . . .	310
14.4.2	Back-Projection Method . . . . .	311
14.4.3	Projection Slice Theorem and the Fourier Reconstruction Method . . . . .	313
14.4.4	Filtered Back-Projection Method . . . . .	314
14.4.5	Reconstruction of MR Images from Radial Data . . . . .	316
14.5	Three-Dimensional Radial $k$ -Space Coverage . . . . .	317
14.6	Radial Coverage Versus Cartesian $k$ -Space Coverage . . . . .	320
14.6.1	Image Distortion Due to Off-Resonance Effects: Cartesian Coverage Versus Radial Sampling . . . . .	321
14.6.2	Effects of Motion . . . . .	323
14.6.3	Cartesian Sampling of Radially Collected Data . . . . .	323
<b>15</b>	<b>Signal, Contrast, and Noise</b>	<b>325</b>
15.1	Signal and Noise . . . . .	326
15.1.1	The Voxel Signal . . . . .	326
15.1.2	The Noise in MRI . . . . .	328
15.1.3	Dependence of the Noise on Imaging Parameters . . . . .	328
15.1.4	Improving SNR by Averaging over Multiple Acquisitions . . . . .	331
15.1.5	Measurement of $\sigma_0$ and Estimation of SNR . . . . .	333
15.2	SNR Dependence on Imaging Parameters . . . . .	334
15.2.1	Generalized Dependence of SNR in 3D Imaging on Imaging Parameters . . . . .	334
15.2.2	SNR Dependence on Read Direction Parameters . . . . .	336
15.2.3	SNR Dependence on Phase Encoding Parameters . . . . .	340
15.2.4	SNR in 2D Imaging . . . . .	341
15.2.5	Imaging Efficiency . . . . .	342
15.3	Contrast, Contrast-to-Noise, and Visibility . . . . .	342
15.3.1	Contrast and Contrast-to-Noise Ratio . . . . .	343
15.3.2	Object Visibility and the Rose Criterion . . . . .	343
15.4	Contrast Mechanisms in MRI and Contrast Maximization . . . . .	345

15.4.1	Three Important Types of Contrast . . . . .	347
15.4.2	Spin Density Weighting . . . . .	347
15.4.3	$T_1$ -Weighting . . . . .	349
15.4.4	$T_2^*$ -Weighting . . . . .	353
15.4.5	Summary of Contrast Results . . . . .	355
15.4.6	A Special Case: $T_1$ -Weighting and Tissue Nulling with Inversion Recovery . . . . .	356
15.5	Contrast Enhancement with $T_1$ -Shortening Agents . . . . .	358
15.6	Partial Volume Effects, CNR, and Resolution . . . . .	363
15.7	SNR in Magnitude and Phase Images . . . . .	365
15.7.1	Magnitude Image SNR . . . . .	365
15.7.2	Phase Image SNR . . . . .	367
15.8	SNR as a Function of Field Strength . . . . .	368
15.8.1	Frequency Dependence of the Noise in MRI . . . . .	369
15.8.2	SNR Dependence on Field Strength . . . . .	370
<b>16</b>	<b>A Closer Look at Radiofrequency Pulses</b>	<b>375</b>
16.1	Relating RF Fields and Measured Spin Density . . . . .	376
16.1.1	RF Pulse Shapes and Apodization . . . . .	378
16.2	Implementing Slice Selection . . . . .	381
16.3	Calibrating the RF Field . . . . .	383
16.3.1	Checking the RF Profile . . . . .	384
16.4	Solutions of the Bloch Equations . . . . .	387
16.4.1	Low Flip Angle Excitation and Rephasing Gradients . . . . .	388
16.4.2	Dephasing and Rephasing at Large Flip Angles . . . . .	390
16.5	Spatially Varying RF Excitation . . . . .	393
16.5.1	Two-Dimensional ‘Beam’ Excitation . . . . .	394
16.5.2	Time Varying Gradients and Slice Selection . . . . .	397
16.5.3	An Example of Spatially Selective Excitations in the Low Flip Angle Limit . . . . .	398
16.6	RF Pulse Characteristics: Flip Angle and RF Power . . . . .	400
16.6.1	Analysis of Slice Selection Parameters . . . . .	401
16.7	Spin Tagging . . . . .	405
16.7.1	Tagging with Gradients Applied Between RF Pulses . . . . .	405
16.7.2	Multiple RF and Gradient Pulses for Tagging . . . . .	407
16.7.3	Summary of Tagging Applications . . . . .	410
<b>17</b>	<b>Water/Fat Separation Techniques</b>	<b>413</b>
17.1	The Effect of Chemical Shift in Imaging . . . . .	413
17.1.1	Fat Shift Artifact . . . . .	414
17.2	Selective Excitation and Tissue Nulling . . . . .	420
17.2.1	Fat Saturation . . . . .	420
17.2.2	Selective Excitation . . . . .	421

17.2.3	Tissue Nulling with Inversion Recovery . . . . .	425
17.3	Multiple Point Water/Fat Separation Methods . . . . .	428
17.3.1	Gradient Echo Sequence for Water/Fat Separation . . . . .	428
17.3.2	Single-Echo Separation . . . . .	433
17.3.3	Spin Echo Approach . . . . .	436
17.3.4	Two-Point Separation . . . . .	437
17.3.5	Three-Point Separation . . . . .	440
<b>18</b>	<b>Fast Imaging in the Steady State</b>	<b>447</b>
18.1	Short- $T_R$ , Spoiled, Gradient Echo Imaging . . . . .	448
18.1.1	Expression for the Steady-State Incoherent (SSI) Signal . . . . .	450
18.1.2	Contrast-to-noise efficiency for small changes in $T_1$ . . . . .	456
18.1.3	Approach to Incoherent Steady-State . . . . .	460
18.1.4	Generating a Constant Transverse Magnetization . . . . .	463
18.1.5	Nonideal Slice Profile Effects on the SSI Signal . . . . .	465
18.2	Short- $T_R$ , Coherent, Gradient Echo Imaging . . . . .	468
18.2.1	Steady-State Free Precession: The Equilibrium Signal . . . . .	472
18.2.2	Approach to Coherent Steady-State . . . . .	476
18.2.3	Utility of SSC Imaging . . . . .	479
18.3	SSFP Signal Formation Mechanisms . . . . .	481
18.3.1	Magnetization Rotation Effects of an Arbitrary Flip Angle Pulse . . . . .	481
18.3.2	Multi-Pulse Experiments and Echoes . . . . .	484
18.4	Understanding Spoiling Mechanisms . . . . .	498
18.4.1	General Principles of Spoiling . . . . .	498
18.4.2	A Detailed Discussion of Spoiling . . . . .	499
18.4.3	Practical Implementation of Spoiling . . . . .	504
18.4.4	RF Spoiled SSI Sequence Implementation . . . . .	508
<b>19</b>	<b>Segmented <math>k</math>-Space and Echo Planar Imaging</b>	<b>511</b>
19.1	Reducing Scan Times . . . . .	512
19.1.1	Reducing $T_R$ . . . . .	512
19.1.2	Reducing the Number of Phase/Partition Encoding Steps . . . . .	512
19.1.3	Fixing the Number of Acquisitions . . . . .	514
19.1.4	Partial Fourier Data Acquisition . . . . .	514
19.2	Segmented $k$ -Space: Phase Encoding Multiple $k$ -Space Lines per RF Excitation for Gradient Echo Imaging . . . . .	514
19.2.1	Conventional Multiple Echo Acquisition . . . . .	515
19.2.2	Phase Encoding Between Gradient Echoes . . . . .	518
19.3	Echo Planar Imaging (EPI) . . . . .	522
19.3.1	An In-Depth Analysis of the EPI Imaging Parameters . . . . .	525
19.3.2	Signal-to-Noise . . . . .	528
19.4	Alternate Forms of Conventional EPI . . . . .	530
19.4.1	Nonuniform Sampling . . . . .	531
19.4.2	Segmented EPI . . . . .	531
19.4.3	Angled $k$ -Space EPI . . . . .	534

19.4.4	Segmented EPI with Oscillating Gradients . . . . .	539
19.4.5	Trapezoidal Versus Oscillating Waveforms . . . . .	541
19.5	Artifacts and Phase Correction . . . . .	543
19.5.1	Phase Errors and Their Correction . . . . .	543
19.5.2	Chemical Shift and Geometric Distortion . . . . .	545
19.5.3	Geometric Distortion . . . . .	546
19.5.4	$T_2^*$ -Filter Effects . . . . .	548
19.5.5	Ghosting . . . . .	549
19.6	Spiral Forms of EPI . . . . .	549
19.6.1	Square-Spiral EPI . . . . .	549
19.6.2	Spiral EPI . . . . .	553
19.7	An Overview of EPI Properties . . . . .	556
19.7.1	Speed of EPI . . . . .	556
19.7.2	Contrast Mechanisms . . . . .	559
19.7.3	Field-of-View and Resolution in the Phase Encoding Direction . . . . .	559
19.7.4	EPI Safety Issues . . . . .	560
19.8	Phase Encoding Between Spin Echoes and Segmented Acquisition . . . . .	560
19.9	Mansfield 2D to 1D Transformation Insight . . . . .	563
19.9.1	Application of the Fourier Transform Shift Theorem . . . . .	563
19.9.2	Collapsing the 2D Problem to a 1D Problem . . . . .	566
<b>20</b>	<b>Magnetic Field Inhomogeneity Effects and <math>T_2^*</math> Dephasing</b>	<b>569</b>
20.1	Image Distortion Due to Field Effects . . . . .	570
20.1.1	Distortion Due to Background Gradients Parallel to the Read Direction . . . . .	570
20.1.2	Distortion Due to Gradient Perpendicular to the Read Direction . . . . .	575
20.1.3	Slice Select Distortion . . . . .	578
20.2	Echo Shifting Due to Field Inhomogeneities in Gradient Echo Imaging . . . . .	580
20.2.1	Echo Shift in Terms of Number of Sampled Points . . . . .	583
20.2.2	Echo Shift Due to Background Phase/Partition Encoding Gradients . . . . .	585
20.2.3	Echo Shift Due to Background Gradients Parallel to the Slice Select Direction . . . . .	586
20.2.4	Echo Shift Due to Background Gradients Orthogonal to the Slice Select Direction . . . . .	587
20.3	Methods for Minimizing Distortion and Echo Shifting Artifacts . . . . .	587
20.3.1	Distortion Versus Dephasing . . . . .	587
20.3.2	High Resolution and Phase Dispersion . . . . .	589
20.3.3	2D Imaging . . . . .	591
20.3.4	2D Imaging with Variable Rephasing Gradients . . . . .	593
20.3.5	3D Imaging . . . . .	594
20.3.6	Phase Encoded 2D and 3D Imaging with Single-Point Sampling: A Limited Version of CSI . . . . .	599
20.3.7	Spectrally Resolved 2D and 3D Imaging . . . . .	601
20.3.8	Understanding the Recovered Signal with Spectral Collapsing . . . . .	601

20.4	Empirical $T_2^*$ . . . . .	603
20.4.1	Arbitrariness of $T_2^*$ Modeling of Gradient Echo Signal Envelopes . . . . .	603
20.4.2	The Spin Echo Signal Envelope and the Magnetic Field Density of States . . . . .	604
20.4.3	Decaying Signal Envelopes and Integrated Signal Conservation . . . . .	605
20.4.4	Obtaining a Lorentzian Density of States: A Simple Argument . . . . .	609
20.4.5	Predicting the Effects of Arbitrary Field Inhomogeneities on the Image . . . . .	610
20.5	Predicting $T_2^*$ for Random Susceptibility Producing Structures . . . . .	611
20.6	Correcting Geometric Distortion . . . . .	615
<b>21</b>	<b>Random Walks, Relaxation, and Diffusion</b> . . . . .	<b>619</b>
21.1	Simple Model for Intrinsic $T_2$ . . . . .	620
21.1.1	Gaussian Behavior for Random Spin Systems . . . . .	620
21.1.2	Brownian Motion and $T_2$ Signal Loss . . . . .	621
21.2	Simple Model for Diffusion . . . . .	622
21.3	Carr-Purcell Mechanism . . . . .	624
21.4	Meiboom-Gill Improvement . . . . .	626
21.5	The Bloch-Torrey Equation . . . . .	628
21.5.1	The Gradient Echo Case for a Bipolar Pulse . . . . .	629
21.5.2	The Spin Echo Case . . . . .	629
21.5.3	Velocity Compensated Diffusion Weighted Sequences . . . . .	631
21.6	Some Practical Examples of Diffusion Imaging . . . . .	632
<b>22</b>	<b>Spin Density, <math>T_1</math>, and <math>T_2</math> Quantification Methods in MR Imaging</b> . . . . .	<b>637</b>
22.1	Simplistic Estimates of $\rho_0$ , $T_1$ , and $T_2$ . . . . .	638
22.1.1	Spin Density Measurement . . . . .	639
22.1.2	$T_1$ Measurement . . . . .	639
22.1.3	$T_2$ Measurement . . . . .	640
22.2	Estimating $T_1$ and $T_2$ from Signal Ratio Measurements . . . . .	640
22.2.1	$T_1$ Estimation from a Signal Ratio Measurement . . . . .	640
22.2.2	$T_2$ Estimation . . . . .	646
22.3	Estimating $T_1$ and $T_2$ from Multiple Signal Measurements . . . . .	647
22.3.1	Parameter Estimation from Multiple Signal Measurements . . . . .	647
22.3.2	$T_1$ Estimation . . . . .	648
22.3.3	$T_2$ and $T_2^*$ Estimation . . . . .	649
22.4	Other Methods for Spin Density and $T_1$ Estimation . . . . .	649
22.4.1	The Look-Locker Method . . . . .	650
22.4.2	$T_1$ Estimation from SSI Measurements at Multiple Flip Angles . . . . .	653
22.5	Practical Issues Related to $T_1$ and $T_2$ Measurements . . . . .	657
22.5.1	Inaccuracies Due to Nonideal Slice Profile . . . . .	657
22.5.2	Other Sources of Inaccuracies in Relaxation Time and Spin Density Measurements . . . . .	661
22.5.3	Advanced Sequence Design for Relaxation Time and Spin Density Measurements . . . . .	663

22.5.4	Choice of Number of Signal Measurement Points . . . . .	664
22.6	Calibration Materials for Relaxation Time Measurements . . . . .	665
<b>23</b>	<b>Motion Artifacts and Flow Compensation</b>	<b>669</b>
23.1	Effects on Spin Phase from Motion along the Read Direction . . . . .	670
23.1.1	Spin Phase Due to Constant Velocity Flow or Motion in the Read Direction . . . . .	670
23.1.2	Effects of Constant Velocity Flow on the Image . . . . .	673
23.2	Velocity Compensation along the Read and Slice Select Directions . . . . .	675
23.2.1	Velocity Compensation Concepts . . . . .	676
23.2.2	Velocity Compensation along the Slice Select Direction . . . . .	681
23.3	Ghosting Due to Periodic Motion . . . . .	683
23.3.1	Ghosting Due to Periodic Flow . . . . .	683
23.3.2	Sinusoidal Translational Motion . . . . .	683
23.3.3	Examples of Ghosting from Pulsatile Flow . . . . .	687
23.4	Velocity Compensation along Phase Encoding Directions . . . . .	688
23.4.1	Effects of Constant Velocity Flow in the Phase Encoding Direction: The Misregistration Artifact . . . . .	688
23.4.2	Phase Variation View of the Shift Artifact . . . . .	691
23.4.3	Velocity Compensating Phase Encoding Gradients . . . . .	693
23.5	Maximum Intensity Projection . . . . .	698
<b>24</b>	<b>MR Angiography and Flow Quantification</b>	<b>701</b>
24.1	Inflow or Time-of-Flight (TOF) Effects . . . . .	702
24.1.1	Critical Speeds . . . . .	702
24.1.2	Approach to Equilibrium . . . . .	703
24.1.3	2D Imaging . . . . .	704
24.1.4	3D Imaging . . . . .	707
24.1.5	Understanding Inflow Effects for Small Velocities . . . . .	709
24.2	TOF Contrast, Contrast Agents, and Spin Density/ $T_2^*$ -Weighting . . . . .	711
24.2.1	Contrast Agents . . . . .	711
24.2.2	Suppressing Signal from Inflowing Blood Using an Inversion Pulse . .	714
24.2.3	Suppressing Signal from Inflowing Blood Using a Saturation Pulse . .	717
24.3	Phase Contrast and Velocity Quantification . . . . .	719
24.3.1	Phase Subtraction and Complex Division for Measuring Velocity . . .	723
24.3.2	Four-Point Velocity Vector Extraction . . . . .	729
24.4	Flow Quantification . . . . .	730
24.4.1	Cardiac Gating . . . . .	733
<b>25</b>	<b>Magnetic Properties of Tissues: Theory and Measurement</b>	<b>739</b>
25.1	Paramagnetism, Diamagnetism, and Ferromagnetism . . . . .	740
25.1.1	Paramagnetism . . . . .	740
25.1.2	Diamagnetism . . . . .	741
25.1.3	Ferromagnetism . . . . .	742
25.2	Permeability and Susceptibility: The $\vec{H}$ Field . . . . .	744

25.2.1	Permeability and the $\vec{H}$ Field . . . . .	744
25.2.2	Susceptibility . . . . .	744
25.3	Objects in External Fields: The Lorentz Sphere . . . . .	745
25.3.1	Spherical Body . . . . .	747
25.3.2	Infinite Cylindrical Body . . . . .	749
25.3.3	Local Field Cancellation via Molecular Demagnetization . . . . .	751
25.3.4	Sphere and Cylinder Examples Revisited: The Physical Internal Fields . . . . .	752
25.4	Susceptibility Imaging . . . . .	755
25.4.1	Phase Measurements . . . . .	755
25.4.2	Magnitude Measurements . . . . .	758
25.5	Brain Functional MRI and the BOLD Phenomenon . . . . .	760
25.5.1	Estimation of Oxygenation Levels . . . . .	763
25.5.2	Deoxyhemoglobin Concentration and Flow . . . . .	764
25.5.3	Functional MR Imaging (fMRI): An Example . . . . .	765
25.6	Signal Behavior in the Presence of Deoxygenated Blood . . . . .	766
25.6.1	The MR Properties of Blood . . . . .	767
25.6.2	Two-Compartment Partial Volume Effects on Signal Loss . . . . .	768
<b>26</b>	<b>Sequence Design, Artifacts, and Nomenclature</b>	<b>779</b>
26.1	Sequence Design and Imaging Parameters . . . . .	780
26.1.1	Slice Select Gradient . . . . .	780
26.1.2	Phase Encoding Gradient . . . . .	783
26.1.3	Read Gradient . . . . .	784
26.1.4	Data Sampling . . . . .	785
26.2	Early Spin Echo Imaging Sequences . . . . .	785
26.2.1	Single and Multi-Echo Spin Echo Sequences . . . . .	785
26.2.2	Inversion Recovery . . . . .	788
26.2.3	Spin Echo with Phase Encoding Between Echoes . . . . .	789
26.3	Fast Short $T_R$ Imaging Sequences . . . . .	791
26.3.1	Steady-State Incoherent: Gradient Echo . . . . .	791
26.3.2	Steady-State Incoherent: Spin Echo . . . . .	793
26.3.3	Steady-State Coherent Imaging . . . . .	793
26.3.4	Pulse Train Methods . . . . .	796
26.3.5	Magnetization Prepared Sequences . . . . .	797
26.4	Imaging Tricks and Image Artifacts . . . . .	798
26.4.1	Readout Bandwidth . . . . .	799
26.4.2	Dealing with System Instabilities . . . . .	801
26.4.3	DC and Line Artifacts . . . . .	806
26.4.4	Noise Spikes and Constant-Frequency Noise . . . . .	809
26.5	Sequence Adjectives and Nomenclature . . . . .	812
26.5.1	Nomenclature . . . . .	812
26.5.2	Some Other Descriptive Adjectives and Some Specific Examples . . . . .	817
<b>27</b>	<b>Introduction to MRI Coils and Magnets</b>	<b>823</b>
27.1	The Circular Loop as an Example . . . . .	824



27.1.1	Quality of Field . . . . .	826
27.2	The Main Magnet Coil . . . . .	827
27.2.1	Classic Designs . . . . .	827
27.2.2	Desirable Properties of Main Magnets . . . . .	833
27.2.3	Shielding . . . . .	836
27.2.4	Shimming . . . . .	837
27.3	Linearly Varying Field Gradients . . . . .	838
27.3.1	Classic Designs . . . . .	838
27.3.2	Calculating Linearly Varying Fields . . . . .	840
27.3.3	Desirable Properties of Linear Gradient Coils . . . . .	841
27.3.4	Eddy Currents and $dB/dt$ . . . . .	842
27.3.5	Active Shielding . . . . .	844
27.3.6	‘Linearly Varying’ Magnetic Fields . . . . .	844
27.4	RF Transmit and Receive Coils . . . . .	846
27.4.1	Transmit Coils . . . . .	847
27.4.2	Receive Coils or RF Probes . . . . .	848
27.4.3	Classic Designs . . . . .	849
27.4.4	RF Shielding . . . . .	854
27.4.5	Power Deposition . . . . .	854
<b>28</b>	<b>Parallel Imaging</b>	<b>859</b>
28.1	Coil Signals, Their Images, and a One-Dimensional Test Case . . . . .	860
28.1.1	Continuous and Discrete Pairs of Transforms for Multiple Coils . . . . .	861
28.1.2	Supplanting Some Gradient Data with RF Coil Data: A Preview . . . . .	862
28.1.3	A Two-Step Function Example . . . . .	863
28.1.4	Aliasing for the Two-Step Function Example . . . . .	863
28.2	Parallel Imaging with an $x$ -Space Approach . . . . .	865
28.2.1	Perfect Coil Sensitivities . . . . .	866
28.2.2	More Realistic Sensitivities and SENSE . . . . .	867
28.3	Parallel Imaging with a $k$ -Space Approach . . . . .	873
28.3.1	Known Sensitivities and SMASH . . . . .	873
28.3.2	Unknown Sensitivities: AUTO-SMASH and GRAPPA . . . . .	877
28.4	Noise and the $g$ -Factor . . . . .	885
28.4.1	SNR and $g$ -Factor Derivation . . . . .	885
28.4.2	$g$ -Factor Example . . . . .	887
28.5	Additional Topics in Acquisition and Reconstruction . . . . .	888
28.5.1	Parallel Transmit Coils . . . . .	888
28.5.2	Interpolation, Extrapolation, and Randomization . . . . .	889
<b>A</b>	<b>Electromagnetic Principles: A Brief Overview</b>	<b>893</b>
A.1	Maxwell’s Equations . . . . .	894
A.2	Faraday’s Law of Induction . . . . .	894
A.3	Electromagnetic Forces . . . . .	895
A.4	Dipoles in an Electromagnetic Field . . . . .	896

A.5	Formulas for Electromagnetic Energy . . . . .	896
A.6	Static Magnetic Field Calculations . . . . .	897
<b>B</b>	<b>Statistics</b>	<b>899</b>
B.1	Accuracy Versus Precision . . . . .	899
B.1.1	Mean and Standard Deviation . . . . .	900
B.2	The Gaussian Probability Distribution . . . . .	901
B.2.1	Probability Distribution . . . . .	901
B.2.2	$z$ -Score . . . . .	901
B.2.3	Quoting Errors and Confidence Intervals . . . . .	902
B.3	Type I and Type II Errors . . . . .	902
B.4	Sum over Several Random Variables . . . . .	904
B.4.1	Multiple Noise Sources . . . . .	905
B.5	Rayleigh Distribution . . . . .	906
B.6	Experimental Validation of Noise Distributions . . . . .	907
B.6.1	Histogram Analysis . . . . .	907
B.6.2	Mean and Standard Deviation . . . . .	909
<b>C</b>	<b>Imaging Parameters to Accompany Figures</b>	<b>913</b>
	<b>Index</b>	<b>923</b>

# Foreword to the Second Edition

Jeffrey L. Duerk

Almost 30 years ago, while a graduate student at Case Western Reserve University, I enrolled in a new course: The Physics of Magnetic Resonance Imaging (PHYS 431) that was being offered by Professors Mark Haacke and Robert Brown. Whole-body MR imaging systems had just emerged on the marketplace and the go-go days of MRI were upon us as numerous companies were dramatically ramping up their research and development efforts in this emerging, yet unproven field. In Cleveland alone, there was Picker International (now Philips Medical Systems) and Technicare (now GE); there were almost 20 MR systems in hospitals and at the manufacturers' facilities. The worldwide need for scientists and engineers with excellent preparation in the underlying physics of MR, signal detection,  $k$ -space, and a variety of pulse sequences was clear. Ultimately, over the next few years, PHYS 431 class notes were organized into sections, then chapters, and, eventually, 'the green bible' as we know this book today. Within a few years, it was translated into Chinese. For many, the book has served not only as a textbook, but as a sustaining reference on numerous aspects of NMR and MR imaging. Today, 'Haacke, Brown, Thompson and Venkatesan' has reached 2000 citations and counting.

For me, in the intervening 30 years, I went from a student to an industry-based researcher who still remembers fondly those go-go days, the advances and friendships formed, and the definitive impact that MRI provided in patient care. Upon returning to academia, I have seen my own students cut their teeth on this book, move to industry and academic positions, and go on to adopt it in their own courses. This has been repeated across universities, programs, and institutions around the world. The impact of this seminal teaching book is hard to calculate. Like Abragam before it, the book has achieved its authors' goals of sustainable impact and becoming a classic in the field.

Like all things, the field has changed dramatically since its original publication. Scan times of 25 minutes are now replaced by those of 25 milliseconds, or so, using novel sequences, novel trajectories, and constrained reconstruction. Field strengths of 0.15 T, 0.3 T, and 0.5 T are replaced by the now more common field strengths of 1.5 T and 3.0 T, with 7.0 T, 9.4 T, and higher either solidly established or emerging on the horizon. Gradient strengths have increased from the lowly 3 mT/m 30 years ago to 40 mT/m on many systems today and soon some systems will have the capability of 80 mT/m. Topics that have emerged today were not fully formed at the time of the first edition, and, hence, this version is not only greatly anticipated but also fulfills the promise of the original version in providing solid practical and rigorous theoretical underpinnings, and relevant challenging homework questions. Topics like

parallel imaging via RF receive coils arrays and numerous other technical insights highlight the additions. The challenge, of course, is how to keep a ‘classic’ a classic in such a dynamic and rapidly evolving field as MR imaging. As with the early versions, I tip my hat to the authors for their selection of topics and also their patience in allowing ‘hot’ fields to reach an appropriate level of sustainability and impact before inclusion here.

On behalf of others like me, who grew up (and continue) using ‘the green bible,’ I want to extend my congratulations and thanks to the authors for this new edition. I anxiously await not only the next generation of discoveries it facilitates but also the next generation of scientists it supports. Well done!

Jeffrey L. Duerk, Ph.D.  
Dean, Case Western Reserve University School of Engineering  
Leonard Case Professor  
Professor, Biomedical Engineering & Radiology  
Case Western Reserve University  
Cleveland, OH

June 11, 2013

Hiroyuki Fujita

Studying the second edition of this textbook on MRI physics has connected marvelous memories: my beginning graduate school experience, many early and long-lasting friendships, internships and major responsibilities with leading OEMs, returning to direct physics research at my alma mater, and then incubating and growing an MRI manufacturing company, Quality Electrodynamics. QED's success has led to such recognitions as a Presidential and First Lady's guest of honor at the 2012 State of the Union Address and a 2013 Presidential Award for Export. From my own education to the training of my team to the business awards, this big green book started and buttressed it all.

I can echo Professor Jeff Duerk's words about his start in MRI because I too began by enrolling in PHYS 431, but a decade later. By the 1990s, this 'Physics of Imaging' had become a standard CWRU course for a graduate imaging track in both the physics and the biomedical engineering departments. The notes from this course became the primary teaching tool in MRI, which I refer to here as the big green book. Professor Mark Haacke introduced me to MR imaging before he left Case Western Reserve University to start his own company and research institute. Immediately after this, I began my Ph.D. with Professor Robert Brown in hardware design, a key move in view of QED's rf coil products. Thus began a series of prideful career-long collaborations with Professor Brown that continues to this day.

The big green book provided a foundation for all the CWRU graduate students I knew in MRI. My good friends, Mike Thompson and Norman Cheng, have been promoted from beginning students to achieving co-authorship. Like myself, they studied the course material, and went on to be teaching assistants, lecturers, and faculty. We could see the influence of the venerable physics textbooks such as Jackson's *Classical Electrodynamics* (which influenced the QED name as well!) and Kittel's just-in-time *Thermal Physics* homework. It is satisfying to notice how the 'critical thinking' goals that are so much in the current educational news — connecting new work to old, applying theory to practice, taking a first step even if the second is not yet clear, finding alternatives if one path fails, looking at whether a solution makes sense, and learning to collaborate — are strongly reflected in this textbook's many problems and the lead-up to them. I am currently serving on the U.S. Manufacturing Council committee tasked with advising the Secretary of Commerce. Science education is recognized as having ever-increasing significance when discussing national policies necessary to improve the current and future workforce in America. I feel that the big green book is emblematic as a key tool in connecting physics and math to imaging science, biology, and chemistry, and preparing the student for an important high-tech career. This is a real teaching tool well received by many generations of CWRU students.

The rf material added in the second edition, especially in the new Chapter 28 on parallel imaging, is really welcome. Over the past decade, my industrial colleagues and I have constantly referenced this textbook and its chapters on signal-to-noise and contrast analysis, sequence parameters, and especially rf software and hardware topics. The green book is evident on many shelves of our company and, wherever we visit, we often observe that it is so beat-up a new edition is really needed. It is not just the expanded rf treatment that will stimulate folks to replace their (dilapidated) first editions.

As the writer of a foreword in this new edition, I perhaps have the responsibility to revisit

the original words by Professor Felix Wehrli to report on what has been added. The book continues to be most appropriate for the physics and engineering graduate and advanced undergraduate classes, with the first two years of math and science in typical technical university curricula as sufficient prerequisites. On the face of it, this second edition is not changed terribly much, with one chapter added to the original twenty-seven. Besides new material in Chapters 17 and 28, however, there seem to be countless improvements found throughout the text and, particularly, the problems. With the new material taking us to a 1000-page book, the authors can be forgiven the omission of some topics such as diffusion tensor weighted imaging. I do know in practice they tend to emphasize hardware better by teaching the material in Chapter 27 earlier in the semester, and I suggest other instructors adopting this text do the same. In my world one can understand why I believe this is a very good suggestion.

Professor Wehrli spoke of ‘exceptional didactic skill’ and predicted ‘*Magnetic Resonance Imaging: Physical Principles and Sequence Design* is likely to become the daily companion of the MRI scientist and a reference standard for years to come.’ I believe his prediction came true. Over the past decade, the book has exceeded 5,000 printed copies and been cited thousands of times, more than those from a number of standard physics textbooks. Its sales have stayed constant right up to the present time. I expect that the new edition will, in the words of Professor Duerk, keep this classic a classic in the coming decade. With my close connections to the authors, customers and contacts in industry and academia often ask me if I know anything about any new edition. After 14 years, I’m thrilled to tell them the second edition is finally here!

Hiroyuki Fujita, Ph.D.  
Quality Electrodynamics LLC  
Mayfield Village, OH

June 28, 2013

# Foreword to the First Edition

Jeffrey L. Duerk

I heard my first lecture on an emerging field in medical imaging known as Nuclear Magnetic Resonance Imaging in 1983 as an electrical engineering graduate student at The Ohio State University. I was captivated and soon moved to Cleveland, a city then considered by many to be a United States center for the development of MR imaging and where both Picker International and Technicare were located a few miles apart. After studying many manuscripts, books and ‘primers,’ I enrolled in a new Physics and Biomedical Engineering course at Case Western Reserve University denoted by PHYS/EBME 431: The Physics of Medical Imaging, taught by Prof. E. Mark Haacke. In large part, the present book has grown and evolved from the class notes and lectures from this course’s offering over the years.

The power of Magnetic Resonance Imaging (MRI) in the diagnostic arena of patient care is unquestionable. A multitude of books exist to assist in the training/teaching of clinicians responsible for interpreting MR images. Since joining the faculty of Case Western Reserve University almost a decade ago, I have been asked by graduate students, new industry hires, and fellow professors (from both CWRU and institutions throughout the world), if there was a book I could recommend which would provide sufficient depth in physics and MR imaging principles to serve as either a textbook or a complete tutorial for basic scientists. In my opinion, there were none which could provide the basic scientist with the tools to understand well the physics of MRI and also understand the engineering challenges necessary to develop the actual acquisitions (known as pulse sequences) which ultimately lead to the images. While there were no single sources available, I implored all to be patient. Today, I believe that patience has been rewarded as the book has arrived.

While much has changed in the field since my introduction to it in the early 1980’s (e.g., the ‘N’ in NMR Imaging and the company Technicare are both gone), the power of this book is that many central concepts in MRI are rather more permanent, and their coverage here is superb. The influence by such notable predecessors as Abragam, Slichter, and Ernst is, at times, unmistakable. Mostly, the personal descriptive and analytical teaching style of Drs. Haacke, Brown, Thompson and Venkatesan builds an understanding of new concepts while clarifying old ones from the solid foundation provided earlier in the text. Another particular advantage of this book is that the notation is consistent, and located in a single reference; the readers do not have to overcome notational differences among our predecessors or difficulties in separating fundamental concepts from advanced material. Importantly, virtually every homework problem in the text has been designed to emphasize a central concept crucial to MRI. When I page through the book, I am often able to find the same derivations in the

homework questions as in my log-books from the early part of my career in MRI. Insights from the authors are present throughout the text as well as within the problems; they provide those less experienced with glimpses (which later become illuminating flashes (no pun intended)) into how MR physics and sequences work and how they can be taken advantage of in the application to new ideas.

While I have been a co-instructor for EBME/PHYS 431 for a number of years and have used drafts of this book as the textbook, by now it bears little resemblance to the class notes of the initial offering in 1985. For that matter, the field of MRI has exploded with new techniques, new applications and far greater understanding and analysis of the innumerable aspects of the MRI hardware and software on image quality. I have benefited from my long friendships with Drs. Haacke and Brown, and the more recent ones with Drs. Thompson and Venkatesan. If you were to walk into the CWRU MRI Laboratory today, you would find no less than five drafts of this book on the shelves. The greatest tribute to these authors in their efforts to compile an important comprehensive treatise on the physics of MRI and MR sequence design can be heard in our research group's discussions of new imaging techniques (and likely those in the future at other institutions world-wide) when someone beckons 'Grab 'Haacke and Brown'!'

Jeffrey L. Duerk, Ph.D.  
Director, Physics Research  
Associate Professor-Departments of Radiology and Biomedical Engineering  
Case Western Reserve University  
Cleveland, OH

January 20, 1999



Felix W. Wehrli

Haacke et al.'s new book spans a significant portion of proton MRI concerned with the design of MRI pulse sequences and image phenomenology. The work, designed for the physicist and engineer, is organized in twenty-seven chapters. The first eight chapters deal with the fundamentals of nuclear magnetic resonance, most of which is based on the classical Bloch formalism, except for a two chapter excursion into quantum mechanics. This portion of the book covers the basic NMR phenomena, and the concepts of signal detection and data acquisition. Chapters 9 and 10 introduce the spatial encoding principles, beginning with one-dimensional Fourier imaging and its logical extension to a second and third spatial dimension. Chapter 11 treats continuous and discrete Fourier transforms, followed in Chapters 12 and 13 by sampling principles, filtering and a discussion of resolution. Chapter 14 may be regarded as the opening section of the book's second part exploring more advanced concepts, beginning with treatment of non-Cartesian imaging and reconstruction. In Chapter 15, the properties of signal-to-noise are dealt with in detail including a discussion of the important scaling laws, followed, in Chapter 16 by a return to a more advanced treatment of rf pulses, along with such concepts as spatially varying rf excitation and spin-tagging. Chapter 17 is dedicated to the various currently practiced methods for water-fat separation, and in Chapters 18 and 19, the authors delve into the ever-growing area of fast imaging techniques. Chapter 18 is entirely dedicated to steady-state gradient-echo imaging methods to which the authors have themselves contributed a great deal since the inception of whole-body MRI. Chapters 19 and 20 address echo train methods focusing on EPI,  $T_2^*$  dephasing effects and the resulting artifacts, ranging from intravoxel phase dispersion to spatial distortion. Chapter 21 is a brief introduction to the physics underlying diffusion-weighted imaging and pertinent measurement techniques. Chapter 22 treats the quantification of the fundamental intrinsic parameters, spin density,  $T_1$  and  $T_2$ . Chapters 23 and 24 deal with the manifestations of motion and flow in terms of the resulting artifacts and their remedies, followed by a broad coverage of the major angiographic and flow quantification methods. The topic of Chapter 25 is induced magnetism and its various manifestations, including a discussion of its most significant application — brain functional MRI exploiting the BOLD phenomenon. In Chapter 26, the authors return to pulse sequence design, reviewing the design criteria for the most important pulse sequences and discussing potential artifacts. The final Chapter 27, at last, discusses hardware in terms of magnets, rf coils and gradients.

This book is the result of a monumental five-year effort by Dr. Haacke and his coauthors to generate a high-level, comprehensive graduate and post-graduate level didactic text on the physics and engineering aspects of MRI. The work clearly targets the methodology of bulk proton imaging, deliberately ignoring chemical shift resolved imaging or treatment of biophysical aspects such as the mechanisms of relaxation in tissues. Understanding the book requires college-level vector calculus. However, many of the basic tools, such as Fourier transforms and the fundamentals of electromagnetism, are elaborated upon either in dedicated chapters or appendices. The problems interspersed in the text of all chapters are a major asset and will be appreciated by student and teacher alike.

There is no doubt that the authors have succeeded in their effort to create a textbook that finally fills a need which has persisted for years. Haacke et al.'s book is, in the reviewer's assessment, the most authoritative new text on the subject, likely to become an essential

tool for anyone actively working on MRI data acquisition and reconstruction techniques, but also for those with a desire to understand MR at a more than superficial level. The work is a rare synthesis of the authors' grasp of the subject, and their extensive practical experience, which they share with the reader through exceptional didactic skill.

The book has few flaws worth mention at all. First, not all chapters provide equal coverage of a targeted topic in that the book often emphasizes areas in which the authors have excelled themselves and thus are particularly experienced. Such a personal slant, of course, is very much in the nature of a treatise written by a single group of authors. On the other hand, the coherence in terms of depth of treatment, quality of illustrations and style, offered here, is never achievable with edited books. A case in point of author-weighted subject treatment is fast imaging, which is heavy on steady-state imaging. The following chapter on echo-train imaging almost exclusively deals with EPI and only secondarily with RARE and its various embodiments. Likewise, diffusion is treated only at its most fundamental level with little mention of anisotropic or restricted diffusion, or diffusion tensor imaging. Though the suggested reading list is helpful, a division into historic articles and those more easily accessible to the student would have been helpful since many of the historic papers cited would have to be retrieved from the library's storage rooms provided they are available at all. Finally, an introduction to the imaging hardware earlier (rather than as the last chapter) would help the novice bridging the gap between theory and instrumentation. None of the above, however, should detract from the book's high quality and practical usefulness.

In summary, the authors need to be congratulated on a superb product; a text vital to those concerned with MRI at a rigorous level. *Magnetic Resonance Imaging: Physical Principles and Sequence Design* is likely to become the daily companion of the MRI scientist and a reference standard for years to come.

Felix W. Wehrli, Ph.D.  
Professor of Radiologic Science and Biophysics  
Editor-in-Chief, *Magnetic Resonance in Medicine*

February 9, 1999

This book is dedicated to our parents:

William James Brown  
Florence Elizabeth Brown

Shih-Tai Cheng  
Tuan-Yu Cheng

Helena Doris Haacke  
Ewart Mortimer Haacke

Robert Thompson  
Mary Christina Thompson

Ramasubramaniam Venkatesan  
Saroja Venkatesan



# Preface to the Second Edition

In the second edition of this book, we have made more improvements and corrections in texts, equations, and homework problems than we can count, enhanced some chapters with new material, added a sizable new chapter, and updated a number of figures in various chapters. In particular, this includes a proof of the equal numbers in discrete Fourier transform pairs in Sec. 12.2.4, the correct interpretation of the  $T_2^*$  filter effect on resolution in Sec. 13.5, revised materials throughout Ch. 16, new material on off-resonance excitation principles in Sec. 17.2.2, optimizing contrast in short- $T_R$  steady-state incoherent imaging in Sec. 18.1.2, a special discussion relating the 2D DFT with a 1D DFT as originally proposed by Professor Peter Mansfield in the 1970s in Sec. 19.9, a rigorous derivation of reducing a 3D dataset to 2D in Sec. 20.3.5, and an introduction to parallel imaging in Ch. 28.

Over the past decade, we indeed followed up our statement of motivation made in the preface to the first edition by teaching hundreds of graduate students and advanced undergraduate students at our home universities. We are aware of many other classes at other universities where the first edition of this book played an important role. MRI education continues to be our primary goal, but we have been gratified by the book's value as a research reference. Limitations remain and, alas, important topics are still missing. There are certain other MRI books that have since appeared and to which we enthusiastically refer the interested reader; we have added them to our suggested readings. To address missing topics, newly emerging topics, and amendments and corrections to the second edition, we have set up a website for students, teachers, and researchers. We are posting the many exam problems and optional homework examples developed in our years of teaching and we offer contacts with lecturers to compare solutions. However, students should try to solve these problems by themselves!

