Lecture Notes in Mechanical Engineering

Niraj Kumar · Szalay Tibor · Rahul Sindhwani · Jaesun Lee · Priyank Srivastava *Editors*

Advances in Interdisciplinary Engineering

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Lecture Notes in Mechanical Engineering

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Preface

This unique and important book presents the concept of interdisciplinary research and offers a timely guide for researchers, professionals from both academia and industry and scientists based on the Second International Conference on Future Learning Aspects of Mechanical Engineering (FLAME 2020), held on August 05–07, 2020, Amity University, Noida, Uttar Pradesh, India. The book presents a selected collection of cutting-edge research articles in interdisciplinary areas such as renewable and green energy, automobile engineering, nano and microelectromechanical systems, ergonomics, navigation and sensor networks, acoustics, biomedical and medical devices, nuclear engineering, agriculture engineering, and farm machineries. This book also provides a snapshot of cutting-edge technologies through practical and theoretical investigations and aims to provide a feasible solution to the challenges faced by the society covering a wide range of topics.

The conference (FLAME 2020) has successfully achieved its aims as it laid a platform for academicians, scientists, and researchers across the globe to share their scientific ideas and vision. This conference also provided opportunities for collaborative research for the benefit of mankind. During the 3 days of the conference, many new ideas pertaining to most recent cutting-edge discoveries were presented and exchanged among 550 participants across the globe.

We take this opportunity to acknowledge the sincere efforts of all authors and the publisher. In addition, we express our gratitude to the Department of Science and Technology (DST), Government of India, Siemens, India, and Begell House. Finally, we would also like to express our gratitude to our Respected Founder President, Amity University, Dr. Ashok K. Chauhan, without his blessings, it would have been impossible to complete this book.

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Contents

SIMP-Based Structural Topology Optimization Using Unstructured Mesh on GPU	1
Shashi Kant Ratnakar, Subhajit Sanfui, and Deepak Sharma	1
Solar-Based Atmospheric Water Generation Device	11
Adoption of Smart Homes in the UK: Customers' Perspective Zainab Oyinlola Ayodimeji, Mukund Janardhanan, Marina Marinelli, and Imran Patel	19
Effect of Temperature on Path and Trajectory Tracking of Mobile Robots in a Cluttered Environment Mohd. Nayab Zafar, J. C. Mohanta, and Md. Faiyaz Ahmed	31
Recent Advances in Performance-Enhancing Parameters of Solar Air-Heater: A Review Swati Mor, Mohmd Usman Khan, Niraj Kumar, Basant Singh Sikarwar, and Gulshan Sachdeva	43
Emerging Security Threats, Countermeasures, Issues, and Future Aspects on the Internet of Things (IoT): A Systematic Literature Review	59
Alliance in Teaching-Learning Strategies and Learning Styles Parul, Jyoti Sarin, Poonam Sheoran, and Rakesh Kumar Phanden	67
Adaptability in Riding Positions: Need for India Shashank Bhardwaj, Jaspreet Hira, Rohit Sharma, Srijit Krishnan, and Puneet K. Jain	77

viii Contents

GPU-Based Topology Optimization Using Matrix-Free Conjugate Gradient Finite Element Solver with Customized Nodal Connectivity Storage	87
Shashi Kant Ratnakar, Subhajit Sanfui, and Deepak Sharma	07
Micro- and Pico-hydroelectric Power Generation: Potential and Future Prospect in Tripura, India Prasanta Majumder, Abhijit Sinha, and Rajat Gupta	99
Surface Roughness Prediction of 3D Printed Surface Using Artificial Neural Networks Akshay Tripathi and Rohit Singla	109
A Fuzzy-Based Decision System to Control and Monitor Mushroom Growth Anita Thakur, Chris Daniel, and Anoop Kumar Shukla	121
Water Contamination and Its Antagonistic Impacts on Human Well-Being—A Case Study of Golden River of East Singhbhum (Subarnarekha River) Sumita Ganguli, Nishi Kant, Sanjeev Sinha, and M. K. Paswan	129
Design of a Low-Cost 1–20 GHz E-Shaped Antenna for Wireless Applications	137
Smart Cattle Feeding Machine for Current Agricultural Scenario Nagesh Patil, Sandeep Tiwari, Niraj Gaikwad, Ajinkya Demda, Shrikant Pangale, and Manmeet Choudhari	145
Identifying the Factors Related to CSR Activities Contributed Toward Brand Management Through Extensive Literature Review	155
Indian Ethos in Marketing Ethics Influencing Consumer Behavior	165
Sensorless Speed Regulation Through AI Controller in Induction Motor	177
Exploring the Probable Applications of Data Mining in the Field of Civil Engineering	185
Economic Implication and Impact of Climate Change on Net Zero Energy Building (NZEB) Ahmad Muhammad Adam, Akanksha Mishra, and Abdullahi Usman	195

Contents ix

Automatic Facial Forgery Detection Using Deep Neural Networks Khushi Chandani and Monika Arora	205
Delamination Detection and Localization in Laminated Structures Using Machine Learning Techniques Trilok Sachin Chittala, Ramesh Gupta Burela, and Sathiskumar Anusuya Ponnusami	215
A Review on Advancements in Photovoltaic Cells	227
Static Analysis of Laminated Composite Stiffened Plates: An Isogeometric Finite Element Approach Ashish Kr. Singh and Anindya Bhar	237
A Review on Real-Time Pothole Detection Techniques	247
Deep Neural Network-Based Facial Emotion Recognition	257
Air Pollution Scenario in India and Assessment of Air Purification Technologies Deepanshu Yadav, Shubhanshu M. Joshi, Mayank Gour, Manander Singh, and Rajeev Kumar Singh	265
Analysis of Key Enablers of Sustainable Additive Manufacturing: A Case of Indian Automotive Company Devarapalli Sai Kishor Reddy, Hema Sudarsan Rao, Chandrakant Sharma, Sumit Gupta, R. K. Shukla, and Ashok Kumar	281
Wheeled Mobile Robot Trajectory Planning Using Evolutionary Techniques	291
DC Fast Charging Technique for Automated Guided Vehicle	303
A Review on Unremitting Growth of Wireless Electricity and Its Escalating Demand in Future Kalp Bhatt, Shriharshini Ganapuram, and Siddhi Vinayak Pandey	313
Lead-Free Solders: Overview, Challenges, and Solutions	321
Effectiveness of Virtual Learning on Knowledge of Students Regarding Covid-19 Amid Its Rapid Upsurges Manisha Saklani, Parvinder Kaur, and Jyoti Sarin	327

x Contents

Dynamically Changing Parameters Particle Swarm Optimization (DCPPSO) Based Trajectory Planning of 3-Links	
Articulated Robot	337
Study of Harmful Effects and Disposal Techniques for E-waste in Emerging Nations. Shyam Sunder and Vinay Pratap Singh	345
PV-Cell-Automated Indoor Integrated Farming	357
A Review on Applications of Simultaneous Localization and Mapping Method in Autonomous Vehicles Subhranil Das, Rashmi Kumari, and S. Deepak Kumar	367
Effectiveness of Japanese Encephalitis Early Warning System Developed by North Eastern Space Application Center in Case Fatality Ratio Mitigation in Three Districts of Assam Soumyabrata Bhattacharjee, Swapnaneel Sarma, and Rajat Kanti Bhattacharjee	377
Service Quality Dimensions in Designing Business Strategies in Urban Bus Transport—A Case for Kolkata Manoj Kumar Shukla, Anurag Shanu, and Lavepreet Singh	383
KisaanMitra: An Autonomous Farm Vehicle with Dual-Axis Solar Tracking Ghanvir Singh, Ayush Sharma, Ankit Mittal, and Ashish Kumar	391
Factors Affecting Travel Range of Electric Vehicles and Their Sustainability Sumit Kumar Sharma, Shubhranshu Srivastava, Shwetansh Gaur, Shubham Sharma, and Ankur Dixit	401
Smart Monitoring and Control System for Exhaust Gases from Vehicles Kurella Sai Eshwar and R. K. Tyagi	413
Hybrid K-Nearest Neighbour and Discriminant Analysis for Predicting Medical Diagnosis in Decision Support System	423
Application of Geometric Poisson Distribution for COVID-19 in Selected States of India	435

Contents xi

To Study Linear Attenuation for Construction of Nuclear Response Robot	447
Prem Narayan Vishwakarma, Tarang Maheshwari, Mohd. Sahil Husain, and Sumit Dubey	777
Design and Development of Hypersonic Aerial Vehicles	457
Development of Vehicular Robots With Machine Learning Capability	469
Himanshu Sengar and Devendra Vashist	107
Assessment of Rice Flour and Jaggery as a Potential 3D Food Printer Cartridge S. Thangalakshmi and Vinkel Kumar Arora	487
Detection of Rust Disease in Wheat Crop Using Convolutional Neural Networks via Transfer Learning Technique	499
Employer Branding Dimensions of Public Sector Undertaking in India and Its Impact on Employee Retention Manisha Singh and Varsha Rokade	509
Pandemic 2020, Challenges, and Measures for Post Revival	529
A Review on Electrical and Mechanical Technologies Used in Spray	#2 0
Painting Robots Siddhi Vinayak Pandey, Shriharshini Ganapuram, Pankti Raval, Aditya Gajjar, Alok Kumar Singh, and Jignesh Thaker	539
Smart Programmed Light Source Calibrated and Software-Based	
Measuring Tool [SPLSC]	547
Path Planning Approaches for Mobile Robot Navigation in Various	
Environments: A Review	555
Battery Storage Systems in Automobiles: A Review	573
A Low Dissipative Scheme for Hyperbolic Conservation Laws Venkata Reddy Poluru	583
Disease Detection and Quality Analysis of Fruits and Vegetables Shweta Tyagi, Anmol Uppal, Rishi Kumar, and Seema Sharma	591

xii Contents

Ranking of Service Quality Attributes in Order of Importance to Choice Rider's in Urban Bus transport—A Case for Kolkata	601
Application of Wavelet Denoising for Phasic Classification in Pick and Place Task Salman Mohd Khan, Abid Ali Khan, and Omar Farooq	609
Determining Optimal Crop Selection by Multi-objective Optimization and Analyzing the Concentration of Heavy Metals Using Chemometric Techniques	617
Development of Green Cementitious Materials Origin from Agro-squander: A Review	629
A Theoretical Review of Anatomy of Net Operating Cycle Vikas Kumar Choubey	647
Development of a Smart Multi-level Car Parking System Prototype	659
Reduction of Noise Emission from Minidor Three Wheeler with Effective Novel Muffler Ali Mohammed, Ramesh Babu Nallamothu, Seshu Kishan Nallamothu, and Anantha Kamal Nallamothu	669
Analysis of the Quadcopter Dynamics with Different Frame Structures Pushpendra Kumar, Faraz Ahmad, and Pravin P. Patil	681
Artificial Neural Networks-Based Robustness Prediction of Bilateral Teleoperated Scooping Motion	689
AC Loss Assessment of 110 kV/5 kA _{rms} HTS Cable for Large Scale Power Application Mohit Kalsia, Mukheshwar Yadav, and Rajneesh Kaushik	699
Quarter Car Model With Power Law Damper Excited by a Road Profile Vipul Paliwal, Ritvik Dobriyal, Pushpendra Kumar, and Niraj Kumar Jha	707
Carrom Playing Robot with Automatic Shot Selection	715

Contents xiii

Performance Comparison Analysis of DCSVCRS and SHVCRS Used in Different Seasons	727
Surender Kumar and Rabinder Singh Bharj	
Hybrid Renewable Road Side Charging Station with I2V Communication Functionality Aswin Mathew, Rohith Babu, Mikhil Thomas Philip, Galvin Thomas Joseph, C. Parag Jose, and K. M. Haneesh	741
Facial Emotion Recognition Model	751
Music Genre Classification Using Machine Learning	763
Review of Cybersecurity Post-COVID-19	775
Optimizing the Effect of Age, Shoulder Height and Feed Force on Muscle Activity and Productivity by Grey Relational Analysis for a Simulated Drilling Task	785
Text-Independent Voice Biometric for User Recognition	799
Input Data Management for Parameter Retrieval by Artificial Neural Network in Third-Grade Fluid Flow Problem Vijay K. Mishra, Chandraneel Pal, Sumanta Chaudhuri, and Santosh K. Hotta	807
Analyzing the Cause–Effect Relationship Among Factors of Social Media Advertising (A Study on Kids' Behavior) Deepika Bandil and Vivek Agrawal	819
Preliminary Investigation of Wind Energy Potential, Availability and Future in the Himalayan State of India: Uttarakhand	829

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SIMP-Based Structural Topology Optimization Using Unstructured Mesh on GPU



1

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Abstract Structural topology optimization is a method of finding optimum material distribution within a given design domain, which is subjected to various loading and support conditions. However, the large computation time is one of the major challenges in its implementation. This challenge gets escalated with the use of unstructured mesh. In this paper, a Solid Isotropic Material with Penalization (SIMP)-based implementation of topology optimization on the graphics processing unit (GPU) for a 3D unstructured mesh is presented. The finite element analysis is performed entirely on a GPU. The main implementation challenges are addressed by developing an efficient and optimized GPU *kernel*. The performance of the implementation is analyzed over an example using three different mesh sizes. Results show almost $4 \times$ speedup over a standard CPU implementation.

Keywords Topology optimization · SIMP · GPU · Unstructured mesh

1 Introduction

Topology optimization is a method for designing lightweight and reliable structures. Its main objective is to find an optimum layout by distributing material in a given design space. The material is distributed in order to achieve the best structural performance in terms of minimizing compliance, cost, or weight of the structure. The topology optimization has been successfully used in mechanical structural design [1], civil structures [2], aerospace structures [3], to name a few.

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2 S. K. Ratnakar et al.

The theoretical aspect of topology optimization is well established. The density-based methods are popular and widely used, particularly SIMP [4]. The density-based methods work on a fixed domain of finite elements and represent a smooth and differentiable problem, which can be solved efficiently by available numerical optimization algorithms.

The SIMP-based topology optimization method begins with the discretization of a design domain, which is known as meshing. In the literature, the structured mesh has been mostly used for meshing solid structures [5]. Structured meshes indeed offer a clear advantage in terms of simplicity of computational implementation, and the amount of computation required. However, their use is limited to simple design problems with regular domain geometry, thereby making their limit applications for real-world problems.

The unstructured meshes are more versatile to discretize domains with complex and irregular geometries. This makes them useful over a wider range of problems, such as those containing nonorthogonal domains and curved boundaries. However, the main challenge is a higher computation time than that with a structured mesh. As topology optimization is already a computationally expensive method, its implementation using unstructured meshes makes it even more computationally challenging.

A viable solution to a high computation time can be found by performing the computation in parallel. The GPU has been very popular in recent years for solving data-parallel computation.

Previous studies used GPU to speedup different parts of topology optimization. The majority of these studies targeted the finite element analysis (FEA) part of the SIMP-based topology optimization [6–8]. Schmidt et al. used GPU to accelerate FEA and gradient computation on a 3D structured mesh. Special attention was given for implementing a sparse matrix–vector product (SpMV) on GPU [5]. Several studies in the literature also computed both FEA and optimization on GPU [9–11]. Methods other than SIMP have also been used with GPU. For example, the level-set method [12] and evolutionary optimization [13] have also been implemented on GPU. Recently, Kiran et al. [14] presented a GPU-based strategy for the generation of finite element stiffness matrices and their assembly. Sanfui et al. [15] used the GPU to accelerate the elemental computation and assembly by exploiting the symmetry. Kiran et al. [16] presented a comparative analysis of the GPU-based solver libraries for a sparse linear system of equations.

Most of the studies discussed above use structured meshes for discretization and analysis. The first work on GPU-based topology optimization using 2D unstructured meshes was presented by Zegard et al. [9]. Later, Duarte et al. [7] presented a GPU-based topology optimization tool PolyTop⁺⁺ using a polygonal mesh. The following are the contributions of this paper.

 Implementation of SIMP-based topology optimization using 3D unstructured mesh on GPU. The implementation is developed using compute unified device architecture (CUDA), to be run on NVIDIA GPUs.