

# Vibration Assisted Machining Theory, Modelling and Applications

Lu Zheng, Wanqun Chen, and Dehong Huo





# **Table of Contents**

**Preface** 

<u>1 Introduction to Vibration-Assisted Machining</u> <u>Technology</u>

<u>1.1 Overview of Vibration-Assisted Machining</u> <u>Technology</u>

1.2 Vibration-Assisted Machining Process

<u>1.3 Applications and Benefits of Vibration-Assisted</u> <u>Machining</u>

1.4 Future Trend of Vibration-Assisted Machining

**References** 

2 Review of Vibration Systems

2.1 Introduction

2.2 Actuators

2.3 Transmission Mechanisms

2.4 Drive and Control

2.5 Vibration-Assisted Machining Systems

2.6 Future Perspectives

2.7 Concluding Remarks

<u>References</u>

<u>3 Vibration System Design and Implementation</u>

3.1 Introduction

3.2 Resonant Vibration System Design

3.3 Nonresonant Vibration System Design

3.4 Concluding Remarks

**References** 

<u>Appendix</u>

4 Kinematics Analysis of Vibration-Assisted Machining

<u>4.1 Introduction</u>

4.2 Kinematics of Vibration-Assisted Turning

4.3 Kinematics of Vibration-Assisted Milling

4.4 Finite Element Simulation of Vibration-Assisted <u>Milling</u>

4.5 Conclusion

<u>References</u>

<u>5 Tool Wear and Burr Formation Analysis in Vibration-Assisted Machining</u>

5.1 Introduction

5.2 Tool Wear

5.3 Burr Formation

5.4 Burr Formation and Classification

5.5 Burr Reduction in Vibration Assisted Machining

5.6 Concluding Remarks

<u>References</u>

<u>6 Modeling of Cutting Force in Vibration-Assisted</u> <u>Machining</u>

6.1 Introduction

6.2 Elliptical Vibration Cutting

6.3 Vibration-Assisted Milling

6.4 Concluding Remarks

<u>References</u>

7 Finite Element Modeling and Analysis of Vibration-Assisted Machining

7.1 Introduction

7.2 Size Effect Mechanism in Vibration-Assisted <u>Micro-milling</u> 7.3 Materials Removal Mechanism in Vibration-Assisted Machining

7.4 Burr Control in Vibration-Assisted Milling

7.5 Verification of Simulation Models

7.6 Concluding Remarks

<u>References</u>

<u>8 Surface Topography Simulation Technology for</u> <u>Vibration-Assisted Machining</u>

8.1 Introduction

8.2 Surface Generation Modeling in Vibration-Assisted Milling

**8.3 Vibration-Assisted Milling Experiments** 

8.4 Discussion and Analysis

8.5 Concluding Remarks

**References** 

**Index** 

End User License Agreement

## List of Tables

Chapter 3

Table 3.1 Relationship between structural correction factors and structural para...

<u>Table 3.2 Vibration stage structural parameters and</u> <u>material properties used in ...</u>

Table 3.3 Comparisons of static and dynamic results.

Table 3.4 Specifications of P-844.20 piezo actuators.

Table 3.5 Specifications of selected DAQ devices.

Table 3.6 Specifications of selected capacitance sensors and controller.

Chapter 4

Table 4.1 Turning cutting types.

<u>Table 4.2 Machining parameters used in the FE</u> <u>simulations.</u>

Chapter 5

<u>Table 5.1 Gibbs free energy of carbon at different</u> <u>temperatures.</u>

<u>Table 5.2 The solubility of carbon in titanium alloy</u> <u>under different temperature...</u>

Chapter 6

Table 6.1 Mechanical properties and parameters for AISI 1045 steel.

Table 6.2 Machining and vibration-assisted parameters.

Table 6.3 The prediction error of maximum and average cutting force between the ...

Chapter 7

Table 7.1 Mechanical properties and materials constant in J–C model for magnesiu...

Chapter 8

Table 8.1 Parameters of the micro-cutting tool.

Table 8.2 HTM from (*oi-xi yi zi*) to (*oj-xj yj zj*).

Table 8.3 State value for each HMT.

Table 8.4 Machining and vibration-assisted parameters.

# List of Illustrations

Chapter 1

Figure 1.1 Schematic of vibration-assisted drilling.

Figure 1.2 Schematic of vibration-assisted turning.

Figure 1.3 Schematic of vibration-assisted grinding.

<u>Figure 1.4 SEM images of burr-free structures</u> <u>made using 2D VAM. Single-crys...</u>

<u>Figure 1.5 Surface texture produced by vibration-</u> <u>assisted machining: (a) mic...</u>

Chapter 2

Figure 2.1 Typical design of a resonant vibrator. Figure 2.2 Vibrator proposed by Zhong et al. Figure 2.3 Vibrator proposed by Shen et al. Figure 2.4 Vibrator proposed by Liu et al. Figure 2.5 Vibrator proposed by Alam et al. Figure 2.6 Vibrator proposed by Babitsky et al. Figure 2.7 Vibrator proposed by Hsu et al. Figure 2.8 Vibrator proposed by Moriwaki and Shamoto. (a) Ultrasonic vibrato... Figure 2.9 Vibrator proposed by Liang et al. Figure 2.11 Vibrator proposed by Börner et al. Figure 2.10 Vibrator proposed by Liu et al. Figure 2.12 Vibrator proposed by Tan et al. Figure 2.13 Vibrator proposed by Suzuki et al. Figure 2.14 Vibrator proposed by Guo and Ehmann. Figure 2.15 Vibrator proposed Yanyan et al.

Figure 2.16 Layout of the 3D vibrator. Figure 2.17 Typical working diagram of a nonresonant vibrator. Figure 2.18 Vibrator proposed by Greco et al. Figure 2.19 Vibrator proposed by Brehl et al. Figure 2.20 Vibrator proposed by Kim et al. Figure 2.21 Vibrator proposed by Chern et al. Figure 2.22 Vibrator proposed by Li et al. Figure 2.23 Vibrator proposed by Lin et al. Figure 2.25 Vibrator proposed by Lin et al. Figure 2.26 Vibrator proposed by Chee et al. Figure 2.27 Layout of a 3D nonresonant vibrator. Figure 2.28 Compound motion-type 3D vibrator.

Chapter 3

<u>Figure 3.1 Schematic of vibration-assisted</u> <u>machining: (a) relative movement ...</u>

<u>Figure 3.2 Schematic diagram of an ultrasonic</u> <u>transducer.</u>

Figure 3.3 Layout of the quarter-wave horn.

<u>Figure 3.4 Finite element analysis mode of the</u> <u>ultrasonic vibrator.</u>

Figure 3.5 First-order longitudinal mode.

<u>Figure 3.6 Displacement response signal at the</u> <u>small end of the horn.</u>

Figure 3.7 Layout of the designed vibration stage.

Figure 3.8 Schematic of flexure hinge.

<u>Figure 3.9 Working principles for the typical flexure</u> <u>mechanism.</u>

Figure 3.10 Compliances model of vibration stage.

Figure 3.11 Dynamic model of the vibration stage.

<u>Figure 3.12 Static FEA simulation of the vibration</u> <u>stage: (a) displacement d...</u>

<u>Figure 3.13 The first two modes of the vibration</u> <u>stage: (a) the first mode o...</u>

<u>Figure 3.14 The architecture and LabVIEW control</u> <u>panel of the control signal...</u>

<u>Figure 3.15 The architecture and LabVIEW control</u> <u>panel of the data collectio...</u>

Figure 3.16 Layout of the control system.

Chapter 4

Figure 4.1 A schematic illustration of vibrationassisted cutting.

Figure 4.2 1D vibration-assisted machining.

Figure 4.3 1D VAM duty cycle chart.

<u>Figure 4.4 Relative speed curve of ultrasonic</u> <u>honing.</u>

Figure 4.5 Schematic illustration of 2D VAM.

Figure 4.6 Duty cycle for 2D VAM as a function of HSR and *d/B* for an ellipti...

<u>Figure 4.7 Schematic diagram of vibration-assisted</u> <u>milling.</u>

Figure 4.8 Type I TWS in VAMILL.

Figure 4.9 Type II TWS in VAMILL.

Figure 4.10 Type III TWS in VAMILL.

<u>Figure 4.11 (a) The region where type 1 separation</u> <u>is likely to occur during...</u>

<u>Figure 4.12 (a) The region where type 1 separation</u> <u>is likely to occur during...</u>

<u>Figure 4.13 Type II separation. (a, b) Schematic</u> <u>diagram and instantaneous u...</u>

<u>Figure 4.14 Type III separation in cross-feed</u> <u>direction. (a, b) The tool tip...</u>

<u>Figure 4.15 Type III separation in feed direction. (a, b) The trajectory of ...</u>

Figure 4.16 FE model of VAMILL.

Figure 4.17 Type I TWS in VAMILL in FE simulation No. 1.

<u>Figure 4.18 Type II TWS in VAMILL in FE</u> <u>simulation No. 2.</u>

<u>Figure 4.19 Type III TWS in VAMILL in FE</u> <u>simulation No. 3.</u>

Chapter 5

Figure 5.1 Classification of tool wear.

Figure 5.2 Layout of tool wear.

<u>Figure 5.3 SEM photographs of worn-out tools: (a)</u> <u>conventional machining, (b...</u>

<u>Figure 5.4 SEM micrograph of the tool flank wear</u> <u>patterns in (a) conventiona...</u>

<u>Figure 5.5 Relative motion between the workpiece</u> <u>and the tool in 1D vibratio...</u>

<u>Figure 5.6 SEM micrographs of cutting tools used</u> <u>in (a) conventional machini...</u> <u>Figure 5.7 Microscope photographs (×1000) of the</u> <u>tool flank faces in the thr...</u>

<u>Figure 5.8 Comparison of average tool forces with</u> <u>distance.</u>

Figure 5.9 Relative motion between the workpiece and the tool in 2D vibratio...

<u>Figure 5.10 Schematic diagram of the contact area</u> <u>between the cutting tool a...</u>

<u>Figure 5.11 SEM micrographs of cutting tools: (a)</u> <u>conventional milling, (b)</u>...

<u>Figure 5.12 Material removal mechanism in</u> <u>micromachining process: (a) elasti...</u>

<u>Figure 5.13 Photos of tool wear: (a) without</u> <u>vibrations and (b) with vibrati...</u>

<u>Figure 5.14 Time history of flank wear land width</u> <u>in conventional machining ...</u>

<u>Figure 5.15 Schematics of Poisson burr, tear burr,</u> <u>and rollover burr.</u>

Figure 5.16 Types of burrs in micro-end milling.

<u>Figure 5.17 Layout of workpiece material</u> <u>deformation zone.</u>

<u>Figure 5.18 Burr height comparison results: (a)</u> <u>vibration-assisted drilling ...</u>

<u>Figure 5.19 SEM photographs of burrs on the</u> <u>workpiece edges: (a) conventiona...</u>

<u>Figure 5.20 The formation of machined surface in</u> <u>micromachining.</u>

<u>Figure 5.21 Machining results comparison between</u> (a) conventional micro-end ... <u>Figure 5.22 Down-milling side tear burr results</u> <u>with different parameters: (...</u>

Chapter 6

Figure 6.1 Elliptical vibration cutting.

Figure 6.2 Tool path.

<u>Figure 6.3 Positional relationship between the tool</u> <u>and the workpiece under ...</u>

<u>Figure 6.4 Transient chip thickness ( $a = c = 4 \mu m$ ,</u> <u> $ufpc = 2 \mu m$ , NDOC = 2, 4,...</u>

<u>Figure 6.5 The tool area of *y*-*z* plane in microgroove generation.</u>

Figure 6.6 Comparison of predicted cutting force in one cycle for *DR* < 1 (*a* ...

Figure 6.7 Comparison of predicted cutting force in one cycle for *DR* > 1 (*a* ...

<u>Figure 6.8 Tool trajectories comparison between</u> <u>the typical conventional mil...</u>

<u>Figure 6.9 Schematics of three types of tool-</u> <u>workpiece separation.</u>

<u>Figure 6.10 Tool tip trajectory of VAMILL. (a)</u> <u>Vibration frequency is an eve...</u>

Figure 6.11 FE model for VAMILL.

Figure 6.12 First set simulation results.

Figure 6.13 Second set simulation results.

Figure 6.14 Third set simulation results.

<u>Figure 6.15 Schematic diagram of typical cutter</u> <u>trajectories in VAMILL.</u> <u>Figure 6.16 Schematic diagram of the other typical</u> <u>cutter trajectories.</u>

<u>Figure 6.17 Cutting force model based on the</u> <u>instantaneous uncut chip thickn...</u>

<u>Figure 6.18 Schematic diagram and experimental</u> <u>setup of the VAMILL system....</u>

<u>Figure 6.19 Simulation results of tool tip</u> <u>trajectories and instantaneous un...</u>

<u>Figure 6.20 Cutting force of 1st set simulation and</u> <u>experiment. (a) *x* direct...</u>

<u>Figure 6.21Figure 6.21 Cutting force of 2nd set</u> <u>simulation and experiment. (...</u>

<u>Figure 6.22Figure 6.22 Cutting force of 3rd set</u> <u>simulation and experiment. (...</u>

<u>Figure 6.23 Micro-milling machine tool with</u> <u>vibration-assisted system; (a) c...</u>

Chapter 7

<u>Figure 7.1 Material removal mechanisms in micro-</u> <u>milling.</u>

<u>Figure 7.2 Comparison of uncut chip thickness</u> <u>between conventional and vibra...</u>

Figure 7.3 FE model of 2D vibration-assisted machining.

<u>Figure 7.4 A comparison between conventional and</u> <u>vibration-assisted machinin...</u>

<u>Figure 7.5 Specific cutting force obtained in</u> <u>conventional machining and vib...</u>

<u>Figure 7.7 Experimental deformed chips during (c)</u> <u>CT, (b) 1D, and (a) 2D UVA...</u> <u>Figure 7.6 (a) Shear-angle graph, (b) strain rate</u> and shear band, (c) chip t...

<u>Figure 7.9 The chip formation with elliptical</u> <u>vibration of 10 kHz. (a-d) Cra...</u>

<u>Figure 7.10 The chip formation with different</u> <u>vibration frequencies. (a–d) C...</u>

<u>Figure 7.8 The chip formation with elliptical</u> <u>vibration of 6 kHz. (a-d) Crac...</u>

<u>Figure 7.11 Comparison of tool trajectory with</u> <u>different vibration frequenci...</u>

<u>Figure 7.12 Stress distribution of (a) VAMM and (b)</u> <u>CMM.</u>

Figure 7.13 Stress comparison in time domain.

<u>Figure 7.14 Cutting force comparison with different</u> <u>vibration frequencies.</u>

<u>Figure 7.15 Schematic diagrams of slot milling: (a)</u> <u>conventional micro-milli...</u>

<u>Figure 7.16 Finite element model of slot milling</u> with vibration assistance i...

<u>Figure 7.17 Slot micro-milling simulation results:</u> (a) conventional, (b) vib...

Figure 7.18 Ti6Al4V machining experiments setup.

<u>Figure 7.19 Tool wear and machined surface test</u> <u>results. (a, b) Tool wear in...</u>

<u>Figure 7.20 Chips with different vibration</u> <u>frequencies.</u>

<u>Figure 7.21 Burr generation. (a) Conventional</u> <u>assisted micro-milling; (b) vi...</u>

Chapter 8

<u>Figure 8.1 Typical structures fabricated with an</u> <u>elliptical ultrasonic textu...</u>

<u>Figure 8.2 Ultrasonic-assisted turning processes for</u> <u>micro-texturing.</u>

<u>Figure 8.3 Flow chart of the surface simulation</u> process.

<u>Figure 8.4 Tool geometry. (a) Side view; (b) top</u> <u>view; (c) corner radius fit...</u>

<u>Figure 8.5 Schematic diagram of vibration-assisted</u> <u>milling.</u>

<u>Figure 8.7 Coordinate transformations: (a)</u> <u>translational transformation, (b-...</u>

<u>Figure 8.6 Coordinate transformations: (a)</u> <u>translational transformation; (b)...</u>

<u>Figure 8.8 The coordinate systems in vibration-</u> <u>assisted milling.</u>

Figure 8.9 Tool instantaneous attitude position.

<u>Figure 8.10 Tool tip trajectories of VAMILL with</u> <u>different RVS. (a) Odd mult...</u>

<u>Figure 8.11 Schematic of surface generation</u> <u>simulation algorithm.</u>

<u>Figure 8.12 Simulation results of the VAM surface.</u> (<u>a-h) Surface generated w...</u>

<u>Figure 8.13 Layout of VAMILL equipment. (a)</u> <u>Vibration-assisted milling syste...</u>

<u>Figure 8.14 Experimental results of the VAM</u> <u>surface. (a-h) Surface generated...</u>

<u>Figure 8.15 Influence of the vibration frequency</u> <u>and amplitude on the contac...</u> <u>Figure 8.16 Influence of the phase difference and</u> <u>vibration frequency on the...</u>

Figure 8.17 Tool wear for fish scale generation.

Figure 8.18 Tool wear for wave surface generation.

# **Wiley-ASME Press Series**

Advanced Multifunctional Lightweight Aerostructures: Design, Development, and Implementation

Kamran Behdinan and Rasool Moradi-Dastjerdi

Vibration Assisted Machining: Theory, Modelling and Applications

Lu Zheng, Wanqun Chen, Dehong Huo

Two-Phase Heat Transfer

Mirza Mohammed Shah

Computer Vision for Structural Dynamics and Health Monitoring

Dongming Feng, Maria Q Feng

Theory of Solid-Propellant Nonsteady Combustion

Vasily B. Novozhilov, Boris V. Novozhilov

Introduction to Plastics Engineering

Vijay K. Stokes

Fundamentals of Heat Engines: Reciprocating and Gas Turbine Internal Combustion Engines

Jamil Ghojel

Offshore Compliant Platforms: Analysis, Design, and Experimental Studies

Srinivasan Chandrasekaran, R. Nagavinothini

Computer Aided Design and Manufacturing

Zhuming Bi, Xiaoqin Wang

Pumps and Compressors

Marc Borremans

Corrosion and Materials in Hydrocarbon Production: A Compendium of Operational and Engineering Aspects

Bijan Kermani and Don Harrop

Design and Analysis of Centrifugal Compressors

Rene Van den Braembussche

Case Studies in Fluid Mechanics with Sensitivities to Governing Variables

M. Kemal Atesmen

The Monte Carlo Ray-Trace Method in Radiation Heat Transfer and Applied Optics

J. Robert Mahan

Dynamics of Particles and Rigid Bodies: A Self-Learning Approach

Mohammed F. Daqaq

Primer on Engineering Standards, Expanded Textbook Edition

Maan H. Jawad and Owen R. Greulich

Engineering Optimization: Applications, Methods and Analysis

R. Russell Rhinehart

Compact Heat Exchangers: Analysis, Design and Optimization using FEM and CFD Approach

C. Ranganayakulu and Kankanhalli N. Seetharamu

Robust Adaptive Control for Fractional-Order Systems with Disturbance and Saturation

Mou Chen, Shuyi Shao, and Peng Shi

Robot Manipulator Redundancy Resolution

Yunong Zhang and Long Jin

Stress in ASME Pressure Vessels, Boilers, and Nuclear Components

Maan H. Jawad

Combined Cooling, Heating, and Power Systems: Modeling, Optimization, and Operation

Yang Shi, Mingxi Liu, and Fang Fang

Applications of Mathematical Heat Transfer and Fluid Flow Models in Engineering and Medicine

Abram S. Dorfman

Bioprocessing Piping and Equipment Design: A Companion Guide for the ASME BPE Standard

William M. (Bill) Huitt

Nonlinear Regression Modeling for Engineering Applications: Modeling, Model Validation, and Enabling Design of Experiments

R. Russell Rhinehart

Geothermal Heat Pump and Heat Engine Systems: Theory and Practice

Andrew D. Chiasson

Fundamentals of Mechanical Vibrations

Liang-Wu Cai

Introduction to Dynamics and Control in Mechanical Engineering Systems

Cho W.S. To

# Vibration Assisted Machining

# Theory, Modelling and Applications

Lu Zheng China Agricultural University

Wanqun Chen Harbin Institute of Technology Harbin, China

Dehong Huo

Newcastle University

Newcastle, UK

This Work is a co-publication between John Wiley & Sons Ltd and ASME Press.



# WILEY

This edition first published 2021

© 2021 John Wiley & Sons. Ltd.

This Work is a co-publication between John Wiley & Sons Ltd and ASME Press.

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording or otherwise, except as permitted by law. Advice on how to obtain permission to reuse material from this title is available at <a href="http://www.wiley.com/go/permissions">http://www.wiley.com/go/permissions</a>.

The right of Lu Zheng, Wanqun Chen, and Dehong Huo to be identified as the authors of this work has been asserted in accordance with law.

#### Registered Offices

John Wiley & Sons, Inc., 111 River Street, Hoboken, NJ 07030, USA

John Wiley & Sons Ltd, The Atrium, Southern Gate, Chichester, West Sussex, PO19 8SQ, UK

#### Editorial Office

The Atrium, Southern Gate, Chichester, West Sussex, PO19 8SQ, UK

For details of our global editorial offices, customer services, and more information about Wiley products visit us at <u>www.wiley.com</u>.

Wiley also publishes its books in a variety of electronic formats and by print-ondemand. Some content that appears in standard print versions of this book may not be available in other formats.

#### *Limit of Liability/Disclaimer of Warranty*

In view of ongoing research, equipment modifications, changes in governmental regulations, and the constant flow of information relating to the use of experimental reagents, equipment, and devices, the reader is urged to review and evaluate the information provided in the package insert or instructions for each chemical, piece of equipment, reagent, or device for, among other things, any changes in the instructions or indication of usage and for added warnings and precautions. While the publisher and authors have used their best efforts in preparing this work, they make no representations or warranties with respect to the accuracy or completeness of the contents of this work and specifically disclaim all warranties, including without limitation any implied warranties of merchantability or fitness for a particular purpose. No warranty may be created or extended by sales representatives, written sales materials or promotional statements for this work. The fact that an organization, website, or product is referred to in this work as a citation and/or potential source of further information does not mean that the publisher and authors endorse the information or services the organization, website, or product may provide or recommendations it may make. This work is sold with the understanding that the publisher is not engaged in rendering professional services. The advice and strategies contained herein may not be suitable for your situation. You should consult with a specialist where appropriate. Further,

readers should be aware that websites listed in this work may have changed or disappeared between when this work was written and when it is read. Neither the publisher nor authors shall be liable for any loss of profit or any other commercial damages, including but not limited to special, incidental, consequential, or other damages.

Library of Congress Cataloging-in-Publication Data

Names: Huo, Dehong, author.

Title: Vibration assisted machining : theory, modelling and applications / Dehong Huo, Newcastle University, Newcastle, UK, Wanqun Chen, Harbin Institute of Technology, Harbin, China, Lu Zheng, China Agricultural University
Description: First edition. | Hoboken, NJ : Wiley, 2021. | Series: Wiley-ASME Press series | Includes bibliographical references.
Identifiers: LCCN 2020027991 (print) | LCCN 2020027992 (ebook) | ISBN 9781119506355 (cloth) | ISBN 9781119506324 (adobe pdf) | ISBN 9781119506362 (epub)
Subjects: LCSH: Machining. | Machine-tools--Vibration. | Cutting--Vibration. | Machinery, Dynamics of.

Classification: LCC TJ1185 .H87 2021 (print) | LCC TJ1185 (ebook) | DDC 671.3/5--dc23

LC record available at https://lccn.loc.gov/2020027991

LC ebook record available at https://lccn.loc.gov/2020027992

Cover Design: Wiley

Cover Image: © microstock3D/Shutterstock

Set in 9.5/12.5pt STIXTwoText by SPi Global, Chennai, India

 $10\;9\;8\;7\;6\;5\;4\;3\;2\;1$ 

# Preface

Precision components are increasingly in demand for various engineering industries, such as biomedical engineering, MEMS, electro-optics, aerospace, and communications. However, processing these difficult-tomachine materials efficiently and economically is always a challenging task, which stimulates the development and subsequent application of vibration-assisted machining (VAM) over the past few decades. Vibration-assisted machining employs additional external energy sources to generate high-frequency vibration in the conventional machining process, changing the machining (cutting) mechanism, thus reducing the cutting force and cutting heat and improving the machining quality. The effective implementation of the VAM process depends on a wide range of technical issues, including vibration device design and setup, process parameter optimization, and performance evaluation. The current awareness on VAM technology is incomplete; although ample review/research papers have been published, no single source provides a comprehensive comprehending yet. Therefore, a book is needed to systematically introduce this emerging manufacturing technology as a subject.

The main objective of this book is to address the basics and the latest advances in the VAM technology. The first chapter provides a brief introduction to VAM technology, including VAM process, benefits, and applications, as well as its history and development, so that the reader would have a general understanding of the subject. The second and third chapters aim to present a detailed description of the characteristics and design process for vibration devices. <u>Chapter 2</u> overviews the current proposed vibration devices in the literature, and the features of each type vibration devices are critically reviewed. Chapter 3 focuses on the implementation and design of vibration devices and the corresponding design procedures are also discussed. Chapters 4 and 5 are dedicated to the effect of vibration and machining parameters on tool path/toolworkpiece separation and the surface topography generation. <u>Chapters 4</u> and <u>5</u> are dedicated to the effect of vibration and machining parameters on tool path/toolworkpiece separation and its influence on the cutting performance. <u>Chapter 4</u> covers the kinematic analysis of VAM, including the tool-workpiece separation type and the corresponding equations during the processing. <u>Chapter 5</u> investigates the mechanisms of tool wear and burr generation under different tool-workpiece separation situations. <u>Chapter 6</u> and <u>7</u> investigate VAM process through simulation modelling method. <u>Chapter 6</u> models the cutting force using both numerical and finite element methods. Finite element modeling and analysis of VAM are detailed in <u>Chapter 7</u> to deeply understand the cutting mechanism of VAM. The last chapter contains the modeling of surface topography using homogeneous matrix transformation and cutter edge sweeping technology, and the results are verified by the machining experiments.

This book provides state of the art in research and engineering practice in VAM for researchers and engineers in the field of mechanical and manufacturing engineering. This book can be used as a textbook for a final year elective subject on manufacturing engineering, or as an introductory subject on advanced manufacturing methods at the postgraduate level. It can also be used as a textbook for teaching advanced manufacturing technology in general. The book can also serve as a useful reference for manufacturing engineers, production supervisors, tooling engineers, planning and application engineers, as well as machine tool designers.

Some of the research findings in this book have arisen from an EPSRC-funded project "Development of a 3D Vibration Assisted Machining System." The authors gratefully acknowledge the financial support of the Engineering and Physical Sciences Research Council (EP/M020657/1).

The authors wish the readers an enjoyable and fruitful reading through the book.

Lu Zheng, Wanqun Chen and Dehong Huo

February 2020

## 1 Introduction to Vibration-Assisted Machining Technology

# **1.1 Overview of Vibration-Assisted Machining Technology**

## 1.1.1 Background

Precision components are increasingly in demand in various engineering fields such as microelectromechanical systems (MEMS), electro-optics, aerospace, automotive, biomedical engineering, and internet and communication technology (ICT) hardware. In addition to the aims of achieving tight tolerances and high-quality surface finishes, many applications also require the use of hard and brittle materials such as optical glass and technical ceramics owing to their superior physical, mechanical, optical, and electronic properties. However, because of their high hardness and usually low fracture toughness, the processing and fabrication of these hard-to-machine materials have always been challenging. Furthermore, the delicate heat treatment required and composite materials in aeronautic or aerospace alloys have caused similar difficulties for precision machining.

It has been reported that excessive tool wear and fracture damage are the main failure modes during the processing of such materials, leading to low surface quality and machining accuracy. Efforts to optimize a conventional machining process to achieve better cutting performance with these materials have never been stopped, and these optimizations include the cutting parameters, tool materials and geometry, and cutting cooling systems in the past decades [<u>1-6</u>]. Generally, harder materials or wear-resistant coatings are applied, and tool geometry is optimized to prevent tool cracking and to reduce wear on wearable positions such as the flank face [<u>5</u>, <u>7-10</u>]. Cryogenic coolants are used in the machining process, and their input pressure has been optimized to achieve better cooling performance [<u>2</u>, <u>4</u>, <u>11</u>]. However, although cutting performance can be improved, the results are often still unsatisfactory.

Efforts to enhance machining performance have revealed that machining quality can be improved using the highfrequency vibration of the tool or workpiece. Vibrationassisted machining (VAM) was first introduced in the late 1950s and has been applied in various machining processes, including both traditional machining (turning, drilling, grinding, and more recently milling) and nontraditional machining (laser machining, electrodischarge machining, and electrochemical machining), and it is now widely used in the precision manufacturing of components made of various materials. VAM adds external energy to the conventional machining process and generate high-frequency, low-amplitude vibration in the tool or workpiece, through which a periodic separation between the uncut workpiece and the tool can be achieved. This can decrease the average machining forces and generate thinner chips, which in turn leads to high processing efficiency, longer tool life, better surface quality and form accuracy, and reduced burr generation [12–17]. Moreover, when hard and brittle materials such as titanium alloy, ceramic, and optical glass are involved, the cutting depth in the ductile regime cutting mode can be increased [18]. As a result, the cutting performance can be improved and unnecessary post-processing can be avoided, which allows the production of components with more complex shape

features [<u>14</u>]. Nevertheless, there are still many opportunities for technological improvement, and ample scope exists for better scientific understanding and exploration.

VAM may be classified in two ways. The first classification is according to the dimensions in which vibration occurs: 1D, 2D, or 3D VAM. The other classification is based on the vibration frequency range, for example, in ultrasonic VAM and non-ultrasonic VAM. Ultrasonic VAM is the most common type of VAM. It works at a high vibration frequency (usually above 20 kHz), and a resonance vibration device maintains the desired vibration amplitude. Most of its applications are concentrated in the machining of hard and brittle materials because of the fact that high vibration frequency dramatically improves the cutting performance of difficult-to-machine materials. Meanwhile non-ultrasonic VAM uses a mechanical linkage to transmit power to make the device expand and contract, and this can obtain lower but variable vibration frequencies (usually less than 10 kHz). It is easier to achieve closed-loop control because of the low range of operating frequency, which makes it uniquely advantageous in applications such as the generation of textured surface.

### **1.1.2 History and Development of Vibration-**Assisted Machining

The history of vibration technology in VAM can be traced back to the 1940s. During the period of World War II, the high demand for the electrically controlled four-way spool valves mainly used in the control of aircraft and gunnery circuits stimulated the development of servo valve technology [19]. Because of their wide frequency response and high flow capacity, electrohydraulic vibrators were successfully developed and applied in VAM in the 1960s with positive effects in enhanced processing quality and

efficiency [20]. With the further development of technology, electromagnetic vibrators featuring higher accuracy and a wide range of frequency and amplitude generation were developed based on electromagnetic technology, and these were successfully applied to various VAM processes [21]. The need for complex hydraulic lines was eliminated, and greater tolerance for the application environment was allowed, which also leads to smaller devices. As a result, a transmission line or connecting body can be attached to the vibrator to achieve a wide range of vibration frequencies and amplitude adjustments [22]. In the 1980s, the maturity of piezoelectric transducer (PZT) piezoelectric ceramic technology had brought a new choice for the vibrator. A piezoelectric ceramic stack could be sandwiched under compressive strain between metal plates, and this has advantages including compactness, high precision and resolution, high frequency response, and large output force [23]. Various shapes of piezoelectric ceramic elements can be used to make different types of vibration actuators, which indicate that the limitations of traditional vibrators were overcome and the application of VAM technology for precision machining was broadened. In addition, it helped in the development of multidimensional VAM equipment. Elliptical VAM has received extensive attention since it was first proposed in the 1990s. Although this process has many advantages compared to its 1D counterpart in terms of reductions in cutting force and prolongation of tool life, it requires higher performance in the vibrator, producing a more accurate tool tip trajectory [24–28]. Piezoelectric actuators with high sensitivity can fulfill the requirements of vibration devices and promote the development of elliptical VAM technology.

## **1.2 Vibration-Assisted Machining Process**

This section briefly introduces commonly used VAM processes, including milling, drilling, turning, grinding, and polishing. Different vibration device layouts are required to implement these vibration-assisted processes and to achieve advantages over the corresponding conventional machining processes.

## 1.2.1 Vibration-Assisted Milling

Milling is one of the most common machining processes and is capable of fabricating parts with complex 3D geometry. However, uncontrollable vibration problems during the cutting process are guite serious and can affect processing stability, especially in the micro-milling process, leading to excessive tolerance, increased surface roughness, and higher cost. Vibration-assisted milling is a processing method that combines the external excitation of periodic vibrations with the relative motion of the milling tool or workpiece to obtain better cutting performance. In addition to the same advantages as other VAM processes, complex surface microstructures can also be obtained because of the combination of a unique tool path and external vibration. Currently, the application of vibrationassisted milling mainly focuses on the one-dimensional direction. The vibration may be applied in the feed direction, cross-feed direction, or axial direction, and tool rotational vibrations may also be applied [14]. Little research has been carried out on 2D vibration-assisted milling because of the difficulty of developing twodimensional vibration platforms (motion coupling and control difficulty), and the vibration mode of these 2D vibration devices mainly involves elliptical vibration and longitudinal torsional vibration.

## 1.2.2 Vibration-Assisted Drilling