

Springer Series in Statistics

Advisors:

P. Bickel, P. Diggle, S. Fienberg, U. Gather,
I. Olkin, S. Zeger

Moshe Shaked
J. George Shanthikumar

Stochastic Orders

 Springer

Moshe Shaked
Department of Mathematics
University of Arizona
Tucson, AZ 85721
shaked@math.arizona.edu

J. George Shanthikumar
Department of Industrial Engineering and Operations Research
University of California, Berkeley
Berkeley, CA 94720
shanthikumar@ieor.berkeley.edu

Library of Congress Control Number: 2006927724

ISBN-10: 0-387-32915-3

ISBN-13: 978-0387-32915-4

Printed on acid-free paper.

© 2007 Springer Science+Business Media, LLC

All rights reserved. This work may not be translated or copied in whole or in part without the written permission of the publisher (Springer Science+Business Media, LLC, 233 Spring Street, New York, NY 10013, USA), except for brief excerpts in connection with reviews or scholarly analysis. Use in connection with any form of information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed is forbidden.

The use in this publication of trade names, trademarks, service marks, and similar terms, even if they are not identified as such, is not to be taken as an expression of opinion as to whether or not they are subject to proprietary rights.

9 8 7 6 5 4 3 2 1

springer.com

To my wife *Edith* and to my children
Tal, Shanna, and Lila

M.S.

To my wife *Mellony* and to my children
Devin, Rajan, and Sohan

J.G.S.

To my wife Edith
and to my children Tal
Shanna
Lila

To my wife Mellony
and to my children Devin
Rajan
Sohan

Preface

Stochastic orders and inequalities have been used during the last 40 years, at an accelerated rate, in many diverse areas of probability and statistics. Such areas include reliability theory, queuing theory, survival analysis, biology, economics, insurance, actuarial science, operations research, and management science. The purpose of this book is to collect in one place essentially all that is known about these orders up to the present. In addition, the book illustrates some of the usefulness and applicability of these stochastic orders.

This book is a major extension of the first six chapters in Shaked and Shanthikumar [515]. The idea that led us to write those six chapters arose as follows. In our own research in reliability theory and operations research we have been using, for years, several notions of stochastic orders. Often we would encounter a result that we could easily (or not so easily) prove, but we could not tell whether it was known or new. Even when we were sure that a result was known, we would not know right away where it could be found. Also, sometimes we would prove a result for the purpose of an application, only to realize later that a stronger result (stronger than what we needed) had already been derived elsewhere. We also often have had difficulties giving a reference for *one* source that contained everything about stochastic orders that we needed in a particular paper. In order to avoid such difficulties we wrote the first six chapters in Shaked and Shanthikumar [515].

Since 1994 the theory of stochastic orders has grown significantly. We think that now is the time to put in one place essentially all that is known about these orders. This book is the result of this effort.

The simplest way of comparing two distribution functions is by the comparison of the associated means. However, such a comparison is based on only two single numbers (the means), and therefore it is often not very informative. In addition to this, the means sometimes do not exist. In many instances in applications one has more detailed information, for the purpose of comparison of two distribution functions, than just the two means. Several orders of distribution functions, that take into account various forms of possible knowl-

edge about the two underlying distribution functions, are studied in Chapters 1 and 2.

When one wishes to compare two distribution functions that have the same mean (or that are centered about the same value), one is usually interested in the comparison of the dispersion of these distributions. The simplest way of doing it is by the comparison of the associated standard deviations. However, such a comparison, again, is based on only two single numbers, and therefore it is often not very informative. In addition to this, again, the standard deviations sometimes do not exist. Several orders of distribution functions, which take into account various forms of possible knowledge about the two underlying distribution functions (in addition to the fact that they are centered about the same value), are studied in Chapter 3. Orders that can be used for the joint comparison of both the location and the dispersion of distribution functions are studied in Chapters 4 and 5. The analogous orders for multivariate distribution functions are studied in Chapters 6 and 7.

When one is interested in the comparison of a sequence of distribution functions, associated with the random variables X_i , $i = 1, 2, \dots$, then one can use, of course, any of the orders described in Chapters 1–7 for the purpose of comparing any two of these distributions. However, the parameter i may now introduce some patterns that connect all the underlying distributions. For example, suppose not only that the random variables X_i , $i = 1, 2, \dots$, increase stochastically in i , but also that the increase is sharper for larger i 's. Then the sequence X_i , $i = 1, 2, \dots$, is stochastically increasing in a convex sense. Such notions of stochastic convexity and concavity are studied in Chapter 8.

Notions of positive dependence of two random variables X_1 and X_2 have been introduced in the literature in an effort to mathematically describe the property that “large (respectively, small) values of X_1 go together with large (respectively, small) values of X_2 .” Many of these notions of positive dependence are defined by means of some comparison of the joint distribution of X_1 and X_2 with their distribution under the theoretical assumption that X_1 and X_2 are independent. Often such a comparison can be extended to general pairs of bivariate distributions with given marginals. This fact led researchers to introduce various notions of positive dependence orders. These orders are designed to compare the strength of the positive dependence of the two underlying bivariate distributions. Many of these orders can be further extended to comparisons of general multivariate distributions that have the same marginals. In Chapter 9 we describe these orders.

We have in mind a wide spectrum of readers and users of this book. On one hand, the text can be useful for those who are already familiar with many aspects of stochastic orders, but who are not aware of all the developments in this area. On the other hand, people who are not very familiar with stochastic orders, but who know something about them, can use this book for the purpose of studying or widening their knowledge and understanding of this important area.

We wish to thank Haijun Li, Asok K. Nanda, and Taizhong Hu for critical readings of several drafts of the manuscript. Their comments led to a substantial improvement in the presentation of some of the results in these chapters. We also thank Yigal Gerchak and Marco Scarsini for some illuminating suggestions. We thank our academic advisors John A. Buzacott (of J. G. S.) and Albert W. Marshall (of M. S.) who, years ago, introduced us to some aspects of the area of stochastic orders.

Tucson, Berkeley,
August 16, 2006

Moshe Shaked
J. George Shanthikumar

Contents

1	Univariate Stochastic Orders	3
1.A	The Usual Stochastic Order	3
1.A.1	Definition and equivalent conditions	3
1.A.2	A characterization by construction on the same probability space	4
1.A.3	Closure properties	5
1.A.4	Further characterizations and properties	8
1.A.5	Some properties in reliability theory	15
1.B	The Hazard Rate Order	16
1.B.1	Definition and equivalent conditions	16
1.B.2	The relation between the hazard rate and the usual stochastic orders	18
1.B.3	Closure properties and some characterizations	18
1.B.4	Comparison of order statistics	31
1.B.5	Some properties in reliability theory	35
1.B.6	The reversed hazard order	36
1.C	The Likelihood Ratio Order	42
1.C.1	Definition	42
1.C.2	The relation between the likelihood ratio and the hazard and reversed hazard orders	43
1.C.3	Some properties and characterizations	44
1.C.4	Shifted likelihood ratio orders	66
1.D	The Convolution Order	70
1.E	Complements	71
2	Mean Residual Life Orders	81
2.A	The Mean Residual Life Order	81
2.A.1	Definition	81
2.A.2	The relation between the mean residual life and some other stochastic orders	83
2.A.3	Some closure properties	86

2.A.4	A property in reliability theory	94
2.B	The Harmonic Mean Residual Life Order	94
2.B.1	Definition	94
2.B.2	The relation between the harmonic mean residual life and some other stochastic orders	95
2.B.3	Some closure properties	97
2.B.4	Properties in reliability theory	105
2.C	Complements	106
3	Univariate Variability Orders	109
3.A	The Convex Order	109
3.A.1	Definition and equivalent conditions	109
3.A.2	Closure and other properties	119
3.A.3	Conditions that lead to the convex order	133
3.A.4	Some properties in reliability theory	138
3.A.5	The m -convex orders	139
3.B	The Dispersive Order	146
3.B.1	Definition and equivalent conditions	146
3.B.2	Properties	151
3.C	The Excess Wealth Order	163
3.C.1	Motivation and definition	163
3.C.2	Properties	165
3.D	The Peakedness Order	171
3.D.1	Definition	171
3.D.2	Some properties	172
3.E	Complements	174
4	Univariate Monotone Convex and Related Orders	181
4.A	The Monotone Convex and Monotone Concave Orders	181
4.A.1	Definitions and equivalent conditions	181
4.A.2	Closure properties and some characterizations	185
4.A.3	Conditions that lead to the increasing convex and increasing concave orders	193
4.A.4	Further properties	197
4.A.5	Some properties in reliability theory	203
4.A.6	The starshaped order	204
4.A.7	Some related orders	206
4.B	Transform Orders: Convex, Star, and Superadditive Orders	213
4.B.1	Definitions	213
4.B.2	Some properties	214
4.B.3	Some related orders	221
4.C	Complements	227

5 The Laplace Transform and Related Orders 233

5.A The Laplace Transform Order 233

 5.A.1 Definitions and equivalent conditions 233

 5.A.2 Closure and other properties 235

5.B Orders Based on Ratios of Laplace Transforms 245

 5.B.1 Definitions and equivalent conditions 245

 5.B.2 Closure properties 246

 5.B.3 Relationship to other stochastic orders 249

5.C Some Related Orders 252

 5.C.1 The factorial moments order 252

 5.C.2 The moments order 255

 5.C.3 The moment generating function order 260

5.D Complements 261

6 Multivariate Stochastic Orders 265

6.A Notations and Preliminaries 265

6.B The Usual Multivariate Stochastic Order 266

 6.B.1 Definition and equivalent conditions 266

 6.B.2 A characterization by construction on the same probability space 266

 6.B.3 Conditions that lead to the multivariate usual stochastic order 267

 6.B.4 Closure properties 273

 6.B.5 Further properties 275

 6.B.6 A property in reliability theory 279

 6.B.7 Stochastic ordering of stochastic processes 280

6.C The Cumulative Hazard Order 286

 6.C.1 Definition 286

 6.C.2 The relationship between the cumulative hazard order and the usual multivariate stochastic order 288

6.D Multivariate Hazard Rate Orders 290

 6.D.1 Definitions and basic properties 290

 6.D.2 Preservation properties 292

 6.D.3 The dynamic multivariate hazard rate order 294

6.E The Multivariate Likelihood Ratio Order 298

 6.E.1 Definition 298

 6.E.2 Some properties 298

 6.E.3 A property in reliability theory 304

6.F The Multivariate Mean Residual Life Order 305

 6.F.1 Definition 305

 6.F.2 The relation between the multivariate mean residual life and the dynamic multivariate hazard rate orders ... 306

 6.F.3 A property in reliability theory 307

6.G Other Multivariate Stochastic Orders 307

 6.G.1 The orthant orders 307

6.G.2	The scaled order statistics orders	314
6.H	Complements	317
7	Multivariate Variability and Related Orders	323
7.A	The Monotone Convex and Monotone Concave Orders	323
7.A.1	Definitions	323
7.A.2	Closure properties	326
7.A.3	Further properties	328
7.A.4	Convex and concave ordering of stochastic processes	330
7.A.5	The (m_1, m_2) -icx orders	331
7.A.6	The symmetric convex order	332
7.A.7	The componentwise convex order	333
7.A.8	The directional convex and concave orders	335
7.A.9	The orthant convex and concave orders	339
7.B	Multivariate Dispersion Orders	342
7.B.1	A strong multivariate dispersion order	342
7.B.2	A weak multivariate dispersion order	344
7.B.3	Dispersive orders based on constructions	346
7.C	Multivariate Transform Orders: Convex, Star, and Superadditive Orders	348
7.D	The Multivariate Laplace Transform and Related Orders	349
7.D.1	The multivariate Laplace transform order	349
7.D.2	The multivariate factorial moments order	352
7.D.3	The multivariate moments order	353
7.E	Complements	354
8	Stochastic Convexity and Concavity	357
8.A	Regular Stochastic Convexity	357
8.A.1	Definitions	358
8.A.2	Closure properties	362
8.A.3	Stochastic m -convexity	365
8.B	Sample Path Convexity	367
8.B.1	Definitions	367
8.B.2	Closure properties	370
8.C	Convexity in the Usual Stochastic Order	374
8.C.1	Definitions	374
8.C.2	Closure properties	376
8.D	Strong Stochastic Convexity	377
8.D.1	Definitions	377
8.D.2	Closure properties	380
8.E	Stochastic Directional Convexity	381
8.E.1	Definitions	381
8.E.2	Closure properties	382
8.F	Complements	384

9 Positive Dependence Orders 387

9.A The PQD and the Supermodular Orders 387

 9.A.1 Definition and basic properties: The bivariate case 387

 9.A.2 Closure properties 390

 9.A.3 The multivariate case 392

 9.A.4 The supermodular order 395

9.B The Orthant Ratio Orders 404

 9.B.1 The (weak) orthant ratio orders 404

 9.B.2 The strong orthant ratio orders 407

9.C The LTD, RTI, and PRD Orders 408

9.D The PLRD Order 414

9.E Association Orders 417

9.F The PDD Order 420

9.G Ordering Exchangeable Distributions 423

9.H Complements 426

References 431

Author Index 459

Subject Index 467

Note

Throughout the book “increasing” means “nondecreasing” and “decreasing” means “nonincreasing.” Expectations are assumed to exist whenever they are written. The “inverse” of a monotone function (which is not strictly monotone) means the right continuous version of it, unless stated otherwise. For example, if F is a distribution function, then the right continuous version of its inverse is $F^{-1}(u) = \sup\{x : F(x) \leq u\}$, $u \in [0, 1]$.

The following aging notions will be encountered often throughout the text. Let X be a random variable with distribution function F and survival function $\bar{F} \equiv 1 - F$.

- (i) The random variable X (or its distribution) is said to be IFR [increasing failure rate] if \bar{F} is logconcave. It is said to be DFR [decreasing failure rate] if \bar{F} is logconvex.
- (ii) The nonnegative random variable X (or its distribution) is said to be IFRA [increasing failure rate average] if $-\log \bar{F}$ is starshaped; that is, if $-\log \bar{F}(t)/t$ is increasing in $t \geq 0$. It is said to be DFRA [decreasing failure rate average] if $-\log \bar{F}$ is antistarshaped; that is, if $-\log \bar{F}(t)/t$ is decreasing in $t \geq 0$.
- (iii) The nonnegative random variable X (or its distribution) is said to be NBU [new better than used] if $\bar{F}(s)\bar{F}(t) \geq \bar{F}(s+t)$ for all $s \geq 0$ and $t \geq 0$. It is said to be NWU [new worse than used] if $\bar{F}(s)\bar{F}(t) \leq \bar{F}(s+t)$ for all $s \geq 0$ and $t \geq 0$.
- (iv) The random variable X (or its distribution) is said to be DMRL [decreasing mean residual life] if $\frac{\int_t^\infty \bar{F}(s)ds}{\bar{F}(t)}$ is decreasing in t over $\{t : \bar{F}(t) > 0\}$. It is said to be IMRL [increasing mean residual life] if $\frac{\int_t^\infty \bar{F}(s)ds}{\bar{F}(t)}$ is increasing in t over $\{t : \bar{F}(t) > 0\}$.
- (v) The nonnegative random variable X (or its distribution) is said to be NBUE [new better than used in expectation] if $\frac{\int_t^\infty \bar{F}(s)ds}{\bar{F}(t)} \leq EX$ for all

$t \geq 0$. It is said to be NWUE [new worse than used in expectation] if $\frac{\int_t^\infty \bar{F}(s) ds}{\bar{F}(t)} \geq EX$ for all $t \geq 0$.

The majorization order will be used in some places in the text. Recall from Marshall and Olkin [383] that a vector $\mathbf{a} = (a_1, a_2, \dots, a_n)$ is said to be smaller in the majorization order than the vector $\mathbf{b} = (b_1, b_2, \dots, b_n)$ (denoted $\mathbf{a} \prec \mathbf{b}$) if $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$ and if $\sum_{i=1}^j a_{[i]} \leq \sum_{i=1}^j b_{[i]}$ for $j = 1, 2, \dots, n-1$, where $a_{[i]}$ [$b_{[i]}$] is the i th largest element of \mathbf{a} [\mathbf{b}], $i = 1, 2, \dots, n$. An n -dimensional function ϕ is called *Schur convex* [*concave*] if $\mathbf{a} \prec \mathbf{b} \implies \phi(\mathbf{a}) \leq [\geq] \phi(\mathbf{b})$.

The notation $\mathbb{N} \equiv \{\dots, -1, 0, 1, \dots\}$, $\mathbb{N}_+ \equiv \{0, 1, \dots\}$, and $\mathbb{N}_{++} \equiv \{1, 2, \dots\}$ will be used in this text.

Univariate Stochastic Orders

In this chapter we study stochastic orders that compare the “location” or the “magnitude” of random variables. The most important and common orders that are considered in this chapter are the usual stochastic order \leq_{st} , the hazard rate order \leq_{hr} , and the likelihood ratio order \leq_{lr} . Some variations of these orders, and some related orders, are also examined in this chapter.

1.A The Usual Stochastic Order

1.A.1 Definition and equivalent conditions

Let X and Y be two random variables such that

$$P\{X > x\} \leq P\{Y > x\} \quad \text{for all } x \in (-\infty, \infty). \quad (1.A.1)$$

Then X is said to be *smaller than Y in the usual stochastic order* (denoted by $X \leq_{\text{st}} Y$). Roughly speaking, (1.A.1) says that X is less likely than Y to take on large values, where “large” means any value greater than x , and that this is the case for all x 's. Note that (1.A.1) is the same as

$$P\{X \leq x\} \geq P\{Y \leq x\} \quad \text{for all } x \in (-\infty, \infty). \quad (1.A.2)$$

It is easy to verify (by noting that every closed interval is an infinite intersection of open intervals) that $X \leq_{\text{st}} Y$ if, and only if,

$$P\{X \geq x\} \leq P\{Y \geq x\} \quad \text{for all } x \in (-\infty, \infty). \quad (1.A.3)$$

In fact, we can recast (1.A.1) and (1.A.3) in a seemingly more general, but actually an equivalent, way as follows:

$$P\{X \in U\} \leq P\{Y \in U\} \quad \text{for all upper sets } U \subseteq (-\infty, \infty). \quad (1.A.4)$$

(In the univariate case, that is on the real line, a set U is an upper set if, and only if, it is an open or a closed right half line.) In the univariate case the

equivalence of (1.A.4) with (1.A.1) and (1.A.3) is trivial, but in Chapter 6 it will be seen that the generalizations of each of these three conditions to the multivariate case yield different definitions of stochastic orders.

Still another way of rewriting (1.A.1) or (1.A.3) is the following:

$$E[I_U(X)] \leq E[I_U(Y)] \quad \text{for all upper sets } U \subseteq (-\infty, \infty), \quad (1.A.5)$$

where I_U denotes the indicator function of U . From (1.A.5) it follows that if $X \leq_{\text{st}} Y$, then

$$E\left[\sum_{i=1}^m a_i I_{U_i}(X)\right] - b \leq E\left[\sum_{i=1}^m a_i I_{U_i}(Y)\right] - b \quad (1.A.6)$$

for all $a_i \geq 0$, $i = 1, 2, \dots, m$, $b \in (-\infty, \infty)$, and $m \geq 0$. Given an increasing function ϕ , it is possible, for each m , to define a sequence of U_i 's, a sequence of a_i 's, and a b (all of which may depend on m), such that as $m \rightarrow \infty$ then (1.A.6) converges to

$$E[\phi(X)] \leq E[\phi(Y)], \quad (1.A.7)$$

provided the expectations exist. It follows that $X \leq_{\text{st}} Y$ if, and only if, (1.A.7) holds for all increasing functions ϕ for which the expectations exist.

The expressions $\int_x^\infty P\{X > y\}dy$ and $\int_x^\infty P\{Y > y\}dy$ are used extensively in Chapters 2, 3, and 4. It is of interest to note that $X \leq_{\text{st}} Y$ if, and only if,

$$\int_x^\infty P\{Y > y\}dy - \int_x^\infty P\{X > y\}dy \quad \text{is decreasing in } x \in (-\infty, \infty). \quad (1.A.8)$$

If X and Y are discrete random variables taking on values in \mathbb{N} , then we have the following. Let $p_i = P\{X = i\}$ and $q_i = P\{Y = i\}$, $i \in \mathbb{N}$. Then $X \leq_{\text{st}} Y$ if, and only if,

$$\sum_{j=-\infty}^i p_j \geq \sum_{j=-\infty}^i q_j, \quad i \in \mathbb{N},$$

or, equivalently, $X \leq_{\text{st}} Y$ if, and only if,

$$\sum_{j=i}^{\infty} p_j \leq \sum_{j=i}^{\infty} q_j, \quad i \in \mathbb{N}.$$

1.A.2 A characterization by construction on the same probability space

An important characterization of the usual stochastic order is the following theorem (here $=_{\text{st}}$ denotes equality in law).

Theorem 1.A.1. *Two random variables X and Y satisfy $X \leq_{\text{st}} Y$ if, and only if, there exist two random variables \hat{X} and \hat{Y} , defined on the same probability space, such that*

$$\hat{X} =_{\text{st}} X, \quad (1.A.9)$$

$$\hat{Y} =_{\text{st}} Y, \quad (1.A.10)$$

and

$$P\{\hat{X} \leq \hat{Y}\} = 1. \quad (1.A.11)$$

Proof. Obviously (1.A.9), (1.A.10), and (1.A.11) imply that $X \leq_{\text{st}} Y$. In order to prove the necessity part of Theorem 1.A.1, let F and G be, respectively, the distribution functions of X and Y , and let F^{-1} and G^{-1} be the corresponding right continuous inverses (see Note on page 1). Define $\hat{X} = F^{-1}(U)$ and $\hat{Y} = G^{-1}(U)$ where U is a uniform $[0, 1]$ random variable. Then it is easy to see that \hat{X} and \hat{Y} satisfy (1.A.9) and (1.A.10). From (1.A.2) it is seen that (1.A.11) also holds. \square

Theorem 1.A.1 is a special case of a more general result that is stated in Section 6.B.2.

From (1.A.2) and Theorem 1.A.1 it follows that the random variables X and Y , with the respective distribution functions F and G , satisfy $X \leq_{\text{st}} Y$ if, and only if,

$$F^{-1}(u) \leq G^{-1}(u), \quad \text{for all } u \in (0, 1). \quad (1.A.12)$$

Another way of restating Theorem 1.A.1 is the following. We omit the obvious proof of it.

Theorem 1.A.2. *Two random variables X and Y satisfy $X \leq_{\text{st}} Y$ if, and only if, there exist a random variable Z and functions ψ_1 and ψ_2 such that $\psi_1(z) \leq \psi_2(z)$ for all z and $X =_{\text{st}} \psi_1(Z)$ and $Y =_{\text{st}} \psi_2(Z)$.*

In some applications, when the random variables X and Y are such that $X \leq_{\text{st}} Y$, one may wish to construct a \hat{Y} [\hat{X}] on the probability space on which X [Y] is defined, such that $\hat{Y} =_{\text{st}} Y$ and $P\{X \leq \hat{Y}\} = 1$ [$\hat{X} =_{\text{st}} X$ and $P\{\hat{X} \leq Y\} = 1$]. This is always possible. Here we will show how this can be done when the distribution function F [G] of X [Y] is absolutely continuous. When this is the case, $F(X)$ [$G(Y)$] is uniformly distributed on $[0, 1]$, and therefore $\hat{Y} = G^{-1}(F(X))$ [$\hat{X} = F^{-1}(G(Y))$] is the desired construction \hat{Y} [\hat{X}].

1.A.3 Closure properties

Using (1.A.1) through (1.A.11) it is easy to prove each of the following closure results. The following notation will be used: For any random variable Z and an event A , let $[Z|A]$ denote any random variable that has as its distribution the conditional distribution of Z given A .

- Theorem 1.A.3.** (a) If $X \leq_{\text{st}} Y$ and g is any increasing [decreasing] function, then $g(X) \leq_{\text{st}} [\geq_{\text{st}}] g(Y)$.
- (b) Let X_1, X_2, \dots, X_m be a set of independent random variables and let Y_1, Y_2, \dots, Y_m be another set of independent random variables. If $X_i \leq_{\text{st}} Y_i$ for $i = 1, 2, \dots, m$, then, for any increasing function $\psi : \mathbb{R}^m \rightarrow \mathbb{R}$, one has

$$\psi(X_1, X_2, \dots, X_m) \leq_{\text{st}} \psi(Y_1, Y_2, \dots, Y_m).$$

In particular,

$$\sum_{j=1}^m X_j \leq_{\text{st}} \sum_{j=1}^m Y_j.$$

That is, the usual stochastic order is closed under convolutions.

- (c) Let $\{X_j, j = 1, 2, \dots\}$ and $\{Y_j, j = 1, 2, \dots\}$ be two sequences of random variables such that $X_j \rightarrow_{\text{st}} X$ and $Y_j \rightarrow_{\text{st}} Y$ as $j \rightarrow \infty$, where “ \rightarrow_{st} ” denotes convergence in distribution. If $X_j \leq_{\text{st}} Y_j, j = 1, 2, \dots$, then $X \leq_{\text{st}} Y$.
- (d) Let X, Y , and Θ be random variables such that $[X|\Theta = \theta] \leq_{\text{st}} [Y|\Theta = \theta]$ for all θ in the support of Θ . Then $X \leq_{\text{st}} Y$. That is, the usual stochastic order is closed under mixtures.

In the next result and in the sequel we define $\sum_{j=1}^0 a_j \equiv 0$ for any sequence $\{a_j, j = 1, 2, \dots\}$.

Theorem 1.A.4. Let $\{X_j, j = 1, 2, \dots\}$ be a sequence of nonnegative independent random variables, and let M be a nonnegative integer-valued random variable which is independent of the X_i 's. Let $\{Y_j, j = 1, 2, \dots\}$ be another sequence of nonnegative independent random variables, and let N be a nonnegative integer-valued random variable which is independent of the Y_i 's. If $X_i \leq_{\text{st}} Y_i, i = 1, 2, \dots$, and if $M \leq_{\text{st}} N$, then

$$\sum_{j=1}^M X_j \leq_{\text{st}} \sum_{j=1}^N Y_j.$$

Another related result is given next.

Theorem 1.A.5. Let $\{X_j, j = 1, 2, \dots\}$ be a sequence of nonnegative independent and identically distributed random variables, and let M be a positive integer-valued random variable which is independent of the X_i 's. Let $\{Y_j, j = 1, 2, \dots\}$ be another sequence of independent and identically distributed random variables, and let N be a positive integer-valued random variable which is independent of the Y_i 's. Suppose that for some positive integer K we have that

$$\sum_{j=1}^K X_j \leq_{\text{st}} [\geq_{\text{st}}] Y_1$$

and

$$M \leq_{\text{st}} [\geq_{\text{st}}] KN,$$

then

$$\sum_{j=1}^M X_j \leq_{\text{st}} [\geq_{\text{st}}] \sum_{j=1}^N Y_j.$$

Proof. The assumptions yield

$$\sum_{i=1}^M X_i \leq_{\text{st}} [\geq_{\text{st}}] \sum_{i=1}^{KN} X_i = \sum_{i=1}^N \sum_{j=K(i-1)+1}^{Ki} X_j \leq_{\text{st}} [\geq_{\text{st}}] \sum_{i=1}^N Y_i. \quad \square$$

Consider now a family of distribution functions $\{G_\theta, \theta \in \mathcal{X}\}$ where \mathcal{X} is a subset of the real line \mathbb{R} . Let $X(\theta)$ denote a random variable with distribution function G_θ . For any random variable Θ with support in \mathcal{X} , and with distribution function F , let us denote by $X(\Theta)$ a random variable with distribution function H given by

$$H(y) = \int_{\mathcal{X}} G_\theta(y) dF(\theta), \quad y \in \mathbb{R}.$$

The following result is a generalization of both parts (a) and (c) of Theorem 1.A.3.

Theorem 1.A.6. *Consider a family of distribution functions $\{G_\theta, \theta \in \mathcal{X}\}$ as above. Let Θ_1 and Θ_2 be two random variables with supports in \mathcal{X} and distribution functions F_1 and F_2 , respectively. Let Y_1 and Y_2 be two random variables such that $Y_i \stackrel{\text{st}}{=} X(\Theta_i)$, $i = 1, 2$; that is, suppose that the distribution function of Y_i is given by*

$$H_i(y) = \int_{\mathcal{X}} G_\theta(y) dF_i(\theta), \quad y \in \mathbb{R}, \quad i = 1, 2.$$

If

$$X(\theta) \leq_{\text{st}} X(\theta') \quad \text{whenever } \theta \leq \theta', \tag{1.A.13}$$

and if

$$\Theta_1 \leq_{\text{st}} \Theta_2, \tag{1.A.14}$$

then

$$Y_1 \leq_{\text{st}} Y_2. \tag{1.A.15}$$

Proof. Note that, by (1.A.13), $P\{X(\theta) > y\}$ is increasing in θ for all y . Thus

$$\begin{aligned} P\{Y_1 > y\} &= \int_{\mathcal{X}} P\{X(\theta) > y\} dF_1(\theta) \\ &\leq \int_{\mathcal{X}} P\{X(\theta) > y\} dF_2(\theta) \\ &= P\{Y_2 > y\}, \quad \text{for all } y, \end{aligned}$$

where the inequality follows from (1.A.14) and (1.A.7). Thus (1.A.15) follows from (1.A.1). \square

Note that, using the notation that is introduced below before Theorem 1.A.14, (1.A.13) can be rewritten as $\{X(\theta), \theta \in \mathcal{X}\} \in \text{SI}$.

The following example shows an application of Theorem 1.A.6 in the area of Bayesian imperfect repair; a related result is given in Example 1.B.16.

Example 1.A.7. Let Θ_1 and Θ_2 be two random variables with supports in $\mathcal{X} = (0, 1]$ and distribution functions F_1 and F_2 , respectively. For some survival function \bar{K} , define

$$\bar{G}_\theta = \bar{K}^{1-\theta}, \quad \theta \in (0, 1],$$

and let $X(\theta)$ have the survival function $\bar{K}^{1-\theta}$. Note that (1.A.13) holds because $\bar{K}^{1-\theta}(y) \leq \bar{K}^{1-\theta'}(y)$ for all y whenever $0 < \theta \leq \theta' \leq 1$. Thus, if $\Theta_1 \leq_{\text{st}} \Theta_2$ then Y_i , with survival function \bar{H}_i defined by

$$\bar{H}_i(y) = \int_0^1 \bar{K}^{1-\theta}(y) dF_i(\theta), \quad y \in \mathbb{R}, \quad i = 1, 2,$$

satisfy $Y_1 \leq_{\text{st}} Y_2$.

1.A.4 Further characterizations and properties

Clearly, if $X \leq_{\text{st}} Y$ then $EX \leq EY$. However, as the following result shows, if two random variables are ordered in the usual stochastic order and have the same expected values, they must have the same distribution.

Theorem 1.A.8. *If $X \leq_{\text{st}} Y$ and if $E[h(X)] = E[h(Y)]$ for some strictly increasing function h , then $X =_{\text{st}} Y$.*

Proof. First we prove the result when $h(x) = x$. Let \hat{X} and \hat{Y} be as in Theorem 1.A.1. If $P\{\hat{X} < \hat{Y}\} > 0$, then $EX = E\hat{X} < E\hat{Y} = EY$, a contradiction to the assumption $EX = EY$. Therefore $X =_{\text{st}} \hat{X} = \hat{Y} =_{\text{st}} Y$. Now let h be some strictly increasing function. Observe that if $X \leq_{\text{st}} Y$, then $h(X) \leq_{\text{st}} h(Y)$ and therefore from the above result we have that $h(X) =_{\text{st}} h(Y)$. The strict monotonicity of h yields $X =_{\text{st}} Y$. \square

Other results that give conditions, involving stochastic orders, which imply stochastic equalities, are given in Theorems 3.A.43, 3.A.60, 4.A.69, 5.A.15, 6.B.19, 6.G.12, 6.G.13, and 7.A.14–7.A.16.

As was mentioned above, if $X \leq_{\text{st}} Y$, then $EX \leq EY$. It is easy to find counterexamples which show that the converse is false. However, $X \leq_{\text{st}} Y$ implies other moment inequalities (for example, $EX^3 \leq EY^3$). Thus one may wonder whether $X \leq_{\text{st}} Y$ can be characterized by a collection of moment inequalities. Brockett and Kahane [109, Corollary 1] showed that there exist no finite number of moment inequalities which imply $X \leq_{\text{st}} Y$. In fact, they showed it for many other stochastic orders that are studied later in this book.

In order to state the next characterization we define the following class of bivariate functions:

$$\mathcal{G}_{\text{st}} = \{\phi : \mathbb{R}^2 \rightarrow \mathbb{R} : \phi(x, y) \text{ is increasing in } x \text{ and decreasing in } y\}.$$

Theorem 1.A.9. *Let X and Y be independent random variables. Then $X \leq_{st} Y$ if, and only if,*

$$\phi(X, Y) \leq_{st} \phi(Y, X) \quad \text{for all } \phi \in \mathcal{G}_{st}. \quad (1.A.16)$$

Proof. Suppose that (1.A.16) holds. The function ϕ defined by $\phi(x, y) \equiv x$ belongs to \mathcal{G}_{st} . Therefore $X \leq_{st} Y$.

In order to prove the “only if” part, suppose that $X \leq_{st} Y$. Let $\phi \in \mathcal{G}_{st}$ and define $\psi(x, y) = \phi(x, -y)$. Then ψ is increasing on \mathbb{R}^2 . Since X and Y are independent it follows that X and $-Y$ are independent and also that $-X$ and Y are independent. Since $X \leq_{st} Y$ it follows (for example, from Theorem 1.A.1) that $-Y \leq_{st} -X$. Therefore, by Theorem 1.A.3(b), we have

$$\psi(X, -Y) \leq_{st} \psi(Y, -X),$$

that is,

$$\phi(X, Y) \leq_{st} \phi(Y, X). \quad \square$$

The next result is a similar characterization. In order to state it we need the following notation: Let ϕ_1 and ϕ_2 be two bivariate functions. Denote $\Delta\phi_{21}(x, y) = \phi_2(x, y) - \phi_1(x, y)$. The proof of the following theorem is omitted.

Theorem 1.A.10. *Let X and Y be two independent random variables. Then $X \leq_{st} Y$ if, and only if,*

$$E\phi_1(X, Y) \leq E\phi_2(X, Y)$$

for all ϕ_1 and ϕ_2 which satisfy that, for each y , $\Delta\phi_{21}(x, y)$ decreases in x on $\{x \leq y\}$; for each x , $\Delta\phi_{21}(x, y)$ increases in y on $\{y \geq x\}$; and $\Delta\phi_{21}(x, y) \geq -\Delta\phi_{21}(y, x)$ whenever $x \leq y$.

Another similar characterization is given in Theorem 4.A.36.

Let X and Y be two random variables with distribution functions F and G , respectively. Let $\mathcal{M}(F, G)$ denote the Fréchet class of bivariate distributions with fixed marginals F and G . Abusing notation we write $(\hat{X}, \hat{Y}) \in \mathcal{M}(F, G)$ to mean that the jointly distributed random variables \hat{X} and \hat{Y} have the marginal distribution functions F and G , respectively. The Fortret-Mourier-Wasserstein distance between the finite mean random variables X and Y is defined by

$$d(X, Y) = \inf_{(\hat{X}, \hat{Y}) \in \mathcal{M}(F, G)} \{E|\hat{Y} - \hat{X}|\}. \quad (1.A.17)$$

Theorem 1.A.11. *Let X and Y be two finite mean random variables such that $EX \leq EY$. Then $X \leq_{st} Y$ if, and only if, $d(X, Y) = EY - EX$.*

Proof. Suppose that $d(X, Y) = EY - EX$. The infimum in (1.A.17) is attained for some (\hat{X}, \hat{Y}) , and we have $E|\hat{Y} - \hat{X}| = E(\hat{Y} - \hat{X})$. Therefore $P\{\hat{X} \leq \hat{Y}\} = 1$, and from Theorem 1.A.1 it follows that $X \leq_{st} Y$.

Conversely, suppose that $X \leq_{st} Y$. Let \hat{X} and \hat{Y} be as in Theorem 1.A.1. Then, for any $(X', Y') \in \mathcal{M}(F, G)$ we have that $E|Y' - X'| \geq |EY' - EX'| = E\hat{Y} - E\hat{X}$. Therefore $d(X, Y) = EY - EX$. \square

A simple sufficient condition which implies the usual stochastic order is described next. The following notation will be used. Let $a(x)$ be defined on I , where I is a subset of the real line. The number of sign changes of a in I is defined by

$$S^-(a) = \sup S^-[a(x_1), a(x_2), \dots, a(x_m)], \quad (1.A.18)$$

where $S^-(y_1, y_2, \dots, y_m)$ is the number of sign changes of the indicated sequence, zero terms being discarded, and the supremum in (1.A.18) is extended over all sets $x_1 < x_2 < \dots < x_m$ such that $x_i \in I$ and $m < \infty$. The proof of the next theorem is simple and therefore it is omitted.

Theorem 1.A.12. *Let X and Y be two random variables with (discrete or continuous) density functions f and g , respectively. If*

$$S^-(g - f) = 1 \quad \text{and the sign sequence is } -, +,$$

then $X \leq_{\text{st}} Y$.

Let X_1 be a nonnegative random variable with distribution function F_1 and survival function $\bar{F}_1 \equiv 1 - F_1$. Define the Laplace transform of X_1 by

$$\varphi_{X_1}(\lambda) = \int_0^\infty e^{-\lambda x} dF_1(x), \quad \lambda > 0,$$

and denote

$$\bar{a}_\lambda^{X_1}(n) = \frac{(-1)^n}{n!} \frac{d^n}{d\lambda^n} \left[\frac{1 - \varphi_{X_1}(\lambda)}{\lambda} \right], \quad n \geq 0, \lambda > 0,$$

and

$$\bar{a}_\lambda^{X_1}(n) = \lambda^n \bar{a}_\lambda^{X_1}(n-1), \quad n \geq 1, \lambda > 0.$$

Similarly, for a nonnegative random variable X_2 with distribution function F_2 and survival function $\bar{F}_2 \equiv 1 - F_2$, define $\bar{a}_\lambda^{X_2}(n)$. It can be shown that $\bar{a}_\lambda^{X_1}$ and $\bar{a}_\lambda^{X_2}$ are discrete survival functions (see the proof of the next theorem); denote the corresponding discrete random variables by $N_\lambda(X_1)$ and $N_\lambda(X_2)$. The following result gives a Laplace transform characterization of the order \leq_{st} .

Theorem 1.A.13. *Let X_1 and X_2 be two nonnegative random variables, and let $N_\lambda(X_1)$ and $N_\lambda(X_2)$ be as described above. Then*

$$X_1 \leq_{\text{st}} X_2 \iff N_\lambda(X_1) \leq_{\text{st}} N_\lambda(X_2) \quad \text{for all } \lambda > 0.$$

Proof. First suppose that $X_1 \leq_{\text{st}} X_2$. Select a $\lambda > 0$. Let Z_1, Z_2, \dots , be independent exponential random variables with mean $1/\lambda$. It can be shown that $\bar{a}_\lambda^{X_1}(n) = P\{\sum_{i=1}^n Z_i \leq X_1\}$ and that $\bar{a}_\lambda^{X_2}(n) = P\{\sum_{i=1}^n Z_i \leq X_2\}$. It thus follows that $N_\lambda(X_1) \leq_{\text{st}} N_\lambda(X_2)$.

Now suppose that $N_\lambda(X_1) \leq_{\text{st}} N_\lambda(X_2)$ for all $\lambda > 0$. Select an $x > 0$. Thus $\bar{a}_{n/x}^{X_1}(n) \leq \bar{a}_{n/x}^{X_2}(n)$. Letting $n \rightarrow \infty$, one obtains $\bar{F}_1(x) \leq \bar{F}_2(x)$ for all continuity points x of F_1 and F_2 . Therefore, $X_1 \leq_{\text{st}} X_2$ by (1.A.1). \square

The implication \implies in Theorem 1.A.13 can be generalized as follows. A family of random variables $\{Z(\theta), \theta \in \Theta\}$ (Θ is a subset of the real line) is said to be stochastically increasing in the usual stochastic order (denoted by $\{Z(\theta), \theta \in \Theta\} \in \text{SI}$) if $Z(\theta) \leq_{\text{st}} Z(\theta')$ whenever $\theta \leq \theta'$. Recall from Theorem 1.A.3(a) that if $X_1 \leq_{\text{st}} X_2$, then $g(X_1) \leq_{\text{st}} g(X_2)$ for any increasing function g . The following result gives a stochastic generalization of this fact.

Theorem 1.A.14. *If $\{Z(\theta), \theta \in \Theta\} \in \text{SI}$ and if $X_1 \leq_{\text{st}} X_2$, where X_k and $Z(\theta)$ are independent for $k = 1, 2$ and $\theta \in \Theta$, then $Z(X_1) \leq_{\text{st}} Z(X_2)$.*

Note that Theorem 1.A.14 is a restatement of Theorem 1.A.6.

Let X be a random variable and denote by $X_{(-\infty, a]}$ the truncation of X at a , that is, $X_{(-\infty, a]}$ has as its distribution the conditional distribution of X given that $X \leq a$. $X_{(a, \infty)}$ is similarly defined. It is simple to prove the following result. Results that are stronger than this are contained in Theorems 1.B.20, 1.B.55, and 1.C.27.

Theorem 1.A.15. *Let X be any random variable. Then $X_{(-\infty, a]}$ and $X_{(a, \infty)}$ are increasing in a in the sense of the usual stochastic order.*

An interesting example in which truncated random variables are compared is the following.

Example 1.A.16. Let $X^{(1)}, X^{(2)}, \dots, X^{(n)}$ be independent and identically distributed random variables. For a fixed t , let $X^{(1)}_{(t, \infty)}, X^{(2)}_{(t, \infty)}, \dots, X^{(n)}_{(t, \infty)}$ be the corresponding truncations, and assume that they are also independent and identically distributed. Then

$$\left(\max\{X^{(1)}, X^{(2)}, \dots, X^{(n)}\}\right)_{(t, \infty)} \leq_{\text{st}} \max\{X^{(1)}_{(t, \infty)}, X^{(2)}_{(t, \infty)}, \dots, X^{(n)}_{(t, \infty)}\},$$

where $\left(\max\{X^{(1)}, X^{(2)}, \dots, X^{(n)}\}\right)_{(t, \infty)}$ denotes the corresponding truncation of $\max\{X^{(1)}, X^{(2)}, \dots, X^{(n)}\}$. The proof consists of a straightforward verification of (1.A.2) for the compared random variables.

Let ϕ_1 and ϕ_2 be two functions that satisfy $\phi_1(x) \leq \phi_2(x)$ for all $x \in \mathbb{R}$, and let X be a random variable. Then, clearly, $\phi_1(X) \leq \phi_2(X)$ almost surely. From Theorem 1.A.1 we thus obtain the following result.

Theorem 1.A.17. *Let X be a random variable and let ϕ_1 and ϕ_2 be two functions that satisfy $\phi_1(x) \leq \phi_2(x)$ for all $x \in \mathbb{R}$. Then*

$$\phi_1(X) \leq_{\text{st}} \phi_2(X).$$

In particular, if ϕ is a function that satisfies $x \leq [\geq] \phi(x)$ for all $x \in \mathbb{R}$, then $X \leq_{\text{st}} [\geq_{\text{st}}] \phi(X)$.

Remark 1.A.18. The set of all distribution functions on \mathbb{R} is a lattice with respect to the order \leq_{st} . That is, if X and Y are random variables with distributions F and G , then there exist random variables Z and W such that $Z \leq_{\text{st}} X$, $Z \leq_{\text{st}} Y$, $W \geq_{\text{st}} X$, and $W \geq_{\text{st}} Y$. Explicitly, Z has the survival function $\min\{\bar{F}, \bar{G}\}$ and W has the survival function $\max\{\bar{F}, \bar{G}\}$.

The next four theorems give conditions under which the corresponding spacings are ordered according to the usual stochastic order. Let X_1, X_2, \dots, X_m be any random variables with the corresponding order statistics $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(m)}$. Define the corresponding spacings by $U_{(i)} = X_{(i)} - X_{(i-1)}$, $i = 2, 3, \dots, m$. When the dependence on m is to be emphasized, we will denote the spacings by $U_{(i:m)}$.

Theorem 1.A.19. *Let $X_1, X_2, \dots, X_m, X_{m+1}$ be independent and identically distributed IFR (DFR) random variables. Then*

$$(m - i + 1)U_{(i:m)} \geq_{\text{st}} [\leq_{\text{st}}] (m - i)U_{(i+1:m)}, \quad i = 2, 3, \dots, m - 1,$$

and

$$(m - i + 2)U_{(i:m+1)} \geq_{\text{st}} [\leq_{\text{st}}] (m - i + 1)U_{(i:m)}, \quad i = 2, 3, \dots, m.$$

The proof of Theorem 1.A.19 is not given here. A stronger version of the DFR part of Theorem 1.A.19 is given in Theorem 1.B.31. Some of the conclusions of Theorem 1.A.19 can be obtained under different conditions. These are stated in the next two theorems. Again, the proofs are not given. In the next two theorems we take $X_{(0)} \equiv 0$, and thus $U_{(1)} = X_{(1)}$. For the following theorem recall from page 1 the definition of Schur concavity.

Theorem 1.A.20. *Let X_1, X_2, \dots, X_m be nonnegative random variables with an absolutely continuous joint distribution function. If the joint density function of X_1, X_2, \dots, X_m is Schur concave (Schur convex), then*

$$(m - i + 1)U_{(i:m)} \geq_{\text{st}} [\leq_{\text{st}}] (m - i)U_{(i+1:m)}, \quad i = 1, 2, \dots, m - 1.$$

Theorem 1.A.21. *Let X_1, X_2, \dots, X_m be independent exponential random variables with possibly different parameters. Then*

$$(m - i + 1)U_{(i:m)} \leq_{\text{st}} (m - i)U_{(i+1:m)}, \quad i = 1, 2, \dots, m - 1.$$

Theorem 1.A.22. *Let X_1, X_2, \dots, X_m be independent and identically distributed random variables with a finite support, and with an increasing [decreasing] density function over that support. Then*

$$U_{(i:m)} \geq_{\text{st}} [\leq_{\text{st}}] U_{(i+1:m)}, \quad i = 2, 3, \dots, m - 1.$$

The proof of Theorem 1.A.22 uses the likelihood ratio order, and therefore it is deferred to Section 1.C, Remark 1.C.3.

Note that any absolutely continuous DFR random variable has a decreasing density function. Thus we see that the assumption in the DFR part of Theorem 1.A.19 is stronger than the assumption in the decreasing part of Theorem 1.A.22, but the conclusion in the DFR part of Theorem 1.A.19 is stronger than the conclusion in the decreasing part of Theorem 1.A.22. It is

of interest to compare Theorems 1.A.19–1.A.22 with Theorems 1.B.31 and 1.C.42.

From Theorem 1.A.1 it is obvious that if $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(m)}$ are the order statistics corresponding to the random variables X_1, X_2, \dots, X_m , then $X_{(1)} \leq_{\text{st}} X_{(2)} \leq_{\text{st}} \dots \leq_{\text{st}} X_{(m)}$. Now let $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(m)}$ be the order statistics corresponding to the random variables X_1, X_2, \dots, X_m , and let $Y_{(1)} \leq Y_{(2)} \leq \dots \leq Y_{(m)}$ be the order statistics corresponding to the random variables Y_1, Y_2, \dots, Y_m . As usual, for any distribution function F , we let $\bar{F} \equiv 1 - F$ denote the corresponding survival function.

Theorem 1.A.23. (a) *Let X_1, X_2, \dots, X_m be independent random variables with distribution functions F_1, F_2, \dots, F_m , respectively. Let Y_1, Y_2, \dots, Y_m be independent and identically distributed random variables with a common distribution function G . Then $X_{(i)} \leq_{\text{st}} Y_{(i)}$ for all $i = 1, 2, \dots, m$ if, and only if,*

$$\prod_{j=1}^m F_j(x) \geq G^m(x) \quad \text{for all } x;$$

that is, if, and only if, $X_{(m)} \leq_{\text{st}} Y_{(m)}$.

(b) *Let X_1, X_2, \dots, X_m be independent random variables with survival functions $\bar{F}_1, \bar{F}_2, \dots, \bar{F}_m$, respectively. Let Y_1, Y_2, \dots, Y_m be independent and identically distributed random variables with a common survival function \bar{G} . Then $X_{(i)} \geq_{\text{st}} Y_{(i)}$ for all $i = 1, 2, \dots, m$ if, and only if,*

$$\prod_{j=1}^m \bar{F}_j(x) \geq \bar{G}^m(x) \quad \text{for all } x;$$

that is, if, and only if, $X_{(1)} \geq_{\text{st}} Y_{(1)}$.

The proof of Theorem 1.A.23 is not given here.

More comparisons of order statistics in the usual stochastic order can be found in Theorem 6.B.23 and in Corollary 6.B.24.

The following neat example compares a sum of independent heterogeneous exponential random variables with an Erlang random variable; it is of interest to compare it with Examples 1.B.5 and 1.C.49. We do not give the proof here.

Example 1.A.24. Let X_i be an exponential random variable with mean $\lambda_i^{-1} > 0$, $i = 1, 2, \dots, m$, and assume that the X_i 's are independent. Let Y_i , $i = 1, 2, \dots, m$, be independent, identically distributed, exponential random variables with mean η^{-1} . Then

$$\sum_{i=1}^m X_i \geq_{\text{st}} \sum_{i=1}^m Y_i \iff \sqrt[m]{\lambda_1 \lambda_2 \cdots \lambda_m} \leq \eta.$$

The next example may be compared with Examples 1.B.6, 1.C.51, and 4.A.45.

Example 1.A.25. Let X_i be a binomial random variable with parameters n_i and p_i , $i = 1, 2, \dots, m$, and assume that the X_i 's are independent. Let Y be a binomial random variable with parameters n and p where $n = \sum_{i=1}^m n_i$. Then

$$\sum_{i=1}^m X_i \geq_{\text{st}} Y \iff p \leq \sqrt[n]{p_1^{n_1} p_2^{n_2} \cdots p_m^{n_m}},$$

and

$$\sum_{i=1}^m X_i \leq_{\text{st}} Y \iff 1 - p \leq \sqrt[n]{(1 - p_1)^{n_1} (1 - p_2)^{n_2} \cdots (1 - p_m)^{n_m}}.$$

The following example gives necessary and sufficient conditions for the comparison of normal random variables; it is generalized in Example 6.B.29. See related results in Examples 3.A.51 and 4.A.46.

Example 1.A.26. Let X be a normal random variable with mean μ_X and variance σ_X^2 , and let Y be a normal random variable with mean μ_Y and variance σ_Y^2 . Then $X \leq_{\text{st}} Y$ if, and only if, $\mu_X \leq \mu_Y$ and $\sigma_X^2 = \sigma_Y^2$.

Example 1.A.27. Let the random variable X have a unimodal density, symmetric about 0. Then

$$(X + a)^2 \leq_{\text{st}} (X + b)^2 \quad \text{whenever } |a| \leq |b|.$$

Example 1.A.28. Let \mathbf{X} have a multivariate normal density with mean vector $\mathbf{0}$ and variance-covariance matrix Σ_1 . Let \mathbf{Y} have a multivariate normal density with mean vector $\mathbf{0}$ and variance-covariance matrix $\Sigma_1 + \Sigma_2$, where Σ_2 is a nonnegative definite matrix. Then

$$\|\mathbf{X}\|^2 \leq_{\text{st}} \|\mathbf{Y}\|^2,$$

where $\|\cdot\|$ denotes the Euclidean norm.

The next result involves the total time on test (TTT) transform and the observed TTT random variable. Let F be the distribution function of a nonnegative random variable, and suppose, for simplicity, that 0 is the left endpoint of the support of F . The TTT transform associated with F is defined by

$$H_F^{-1}(u) = \int_0^{F^{-1}(u)} \bar{F}(x) dx, \quad 0 \leq u \leq 1, \tag{1.A.19}$$

where $\bar{F} \equiv 1 - F$ is the survival function associated with F . The inverse, H_F , of the TTT transform is a distribution function. If the mean $\mu = \int_0^\infty x dF(x) = \int_0^\infty \bar{F}(x) dx$ is finite, then H_F has support in $[0, \mu]$. If X has the distribution function F , then let X_{ttt} be any random variable that has the distribution H_F . The random variable X_{ttt} is called the *observed total time on test*.

Theorem 1.A.29. *Let X and Y be two nonnegative random variables. Then*

$$X \leq_{\text{st}} Y \implies X_{\text{ttt}} \leq_{\text{st}} Y_{\text{ttt}}.$$

See related results in Theorems 3.B.1, 4.A.44, 4.B.8, 4.B.9, and 4.B.29.

1.A.5 Some properties in reliability theory

Recall from page 1 the definitions of the IFR, DFR, NBU, and NWU properties. The next result characterizes random variables that have these properties by means of the usual stochastic order. The statements in the next theorem follow at once from the definitions. Recall from Section 1.A.3 that for any random variable Z and an event A we denote by $[Z|A]$ any random variable that has as its distribution the conditional distribution of Z given A .

Theorem 1.A.30. (a) *The random variable X is IFR [DFR] if, and only if, $[X - t|X > t] \geq_{\text{st}} [\leq_{\text{st}}] [X - t'|X > t']$ whenever $t \leq t'$.*
 (b) *The nonnegative random variable X is NBU [NWU] if, and only if, $X \geq_{\text{st}} [\leq_{\text{st}}] [X - t|X > t]$ for all $t > 0$.*

Note that if X is the lifetime of a device, then $[X - t|X > t]$ is the residual life of such a device with age t . Theorem 1.A.30(a), for example, characterizes IFR and DFR random variables by the monotonicity of their residual lives with respect to the order \leq_{st} . Theorem 1.A.30 should be compared to Theorem 1.B.38, where a similar characterization is given. Some multivariate analogs of Theorem 1.A.30(a) are used in Section 6.B.6 to introduce some multivariate IFR notions.

For a nonnegative random variable X with a finite mean, let A_X denote the corresponding asymptotic equilibrium age. That is, if the distribution function of X is F , then the distribution function F_e of A_X is defined by

$$F_e(x) = \frac{1}{EX} \int_0^x \bar{F}(y) dy, \quad x \geq 0, \quad (1.A.20)$$

where $\bar{F} \equiv 1 - F$ is the corresponding survival function. Recall from page 1 the definitions of the NBUE and the NWUE properties. The following result is immediate.

Theorem 1.A.31. *The nonnegative random variable X with finite mean is NBUE [NWUE] if, and only if, $X \geq_{\text{st}} [\leq_{\text{st}}] A_X$.*

Another characterization of NBUE random variables is the following. Recall from Section 1.A.4 the definition of the observed total time on test random variable X_{ttt} .

Theorem 1.A.32. *Let X be a nonnegative random variable with finite mean μ . Then X is NBUE if, and only if,*

$$X_{\text{ttt}} \geq_{\text{st}} \mathcal{U}(0, \mu),$$

where $\mathcal{U}(0, \mu)$ denotes a uniform random variable on $(0, \mu)$.

Let X be a nonnegative random variable with finite mean and distribution function F , and let A_X be the corresponding asymptotic equilibrium age having the distribution function F_e given in (1.A.20). The requirement

$$X \geq_{\text{st}} [A_X - t | A_X > t] \quad \text{for all } t \geq 0, \quad (1.A.21)$$

has been used in the literature as a way to define an aging property of the lifetime X . It turns out that this aging property is equivalent to the new better than used in convex ordering (NBUC) notion that is defined in (4.A.31) in Chapter 4.

1.B The Hazard Rate Order

1.B.1 Definition and equivalent conditions

If X is a random variable with an absolutely continuous distribution function F , then the hazard rate of X at t is defined as $r(t) = (d/dt)(-\log(1 - F(t)))$. The hazard rate can alternatively be expressed as

$$r(t) = \lim_{\Delta t \downarrow 0} \frac{P\{t < X \leq t + \Delta t | X > t\}}{\Delta t} = \frac{f(t)}{\bar{F}(t)}, \quad t \in \mathbb{R}, \quad (1.B.1)$$

where $\bar{F} \equiv 1 - F$ is the survival function and f is the corresponding density function. As can be seen from (1.B.1), the hazard rate $r(t)$ can be thought of as the intensity of failure of a device, with a random lifetime X , at time t . Clearly, the higher the hazard rate is the smaller X should be stochastically. This is the motivation for the order discussed in this section.

Let X and Y be two nonnegative random variables with absolutely continuous distribution functions and with hazard rate functions r and q , respectively, such that

$$r(t) \geq q(t), \quad t \in \mathbb{R}. \quad (1.B.2)$$

Then X is said to be *smaller than Y in the hazard rate order* (denoted as $X \leq_{\text{hr}} Y$).

Although the hazard rate order is usually applied to random lifetimes (that is, nonnegative random variables), definition (1.B.2) may also be used to compare more general random variables. In fact, even the absolute continuity, which is required in (1.B.2), is not really needed. It is easy to verify that (1.B.2) holds if, and only if,

$$\frac{\bar{G}(t)}{\bar{F}(t)} \quad \text{increases in } t \in (-\infty, \max(u_X, u_Y)) \quad (1.B.3)$$

(here $a/0$ is taken to be equal to ∞ whenever $a > 0$). Here F denotes the distribution function of X and G denotes the distribution function of Y , and u_X and u_Y denote the corresponding right endpoints of the supports of X and of Y . Equivalently, (1.B.3) can be written as

$$\bar{F}(x)\bar{G}(y) \geq \bar{F}(y)\bar{G}(x) \quad \text{for all } x \leq y. \quad (1.B.4)$$

Thus (1.B.3) or (1.B.4) can be used to define the order $X \leq_{\text{hr}} Y$ even if X and/or Y do not have absolutely continuous distributions. A useful further condition, which is equivalent to $X \leq_{\text{hr}} Y$ when X and Y have absolutely continuous distributions with densities f and g , respectively, is the following:

$$\frac{f(x)}{\bar{F}(y)} \geq \frac{g(x)}{\bar{G}(y)} \quad \text{for all } x \leq y. \quad (1.B.5)$$

Rewriting (1.B.4) as

$$\frac{\bar{F}(t+s)}{\bar{F}(t)} \leq \frac{\bar{G}(t+s)}{\bar{G}(t)} \quad \text{for all } s \geq 0 \text{ and all } t,$$

it is seen that $X \leq_{\text{hr}} Y$ if, and only if,

$$P\{X-t > s | X > t\} \leq P\{Y-t > s | Y > t\} \quad \text{for all } s \geq 0 \text{ and all } t; \quad (1.B.6)$$

that is, if, and only if, the residual lives of X and Y at time t are ordered in the sense \leq_{st} for all t . Equivalently, (1.B.6) can be written as

$$[X | X > t] \leq_{\text{st}} [Y | Y > t] \quad \text{for all } t. \quad (1.B.7)$$

Substituting $u = \bar{F}^{-1}(t)$ in (1.B.3) shows that $X \leq_{\text{hr}} Y$ if, and only if,

$$\frac{\bar{G}\bar{F}^{-1}(u)}{u} \geq \frac{\bar{G}\bar{F}^{-1}(v)}{v} \quad \text{for all } 0 < u \leq v < 1.$$

Simple manipulations show that the latter condition is equivalent to

$$\frac{1 - FG^{-1}(1-u)}{u} \leq \frac{1 - FG^{-1}(1-v)}{v} \quad \text{for all } 0 < u \leq v < 1. \quad (1.B.8)$$

For discrete random variables that take on values in \mathbb{N} the definition of \leq_{hr} can be written in two different ways. Let X and Y be such random variables. We denote $X \leq_{\text{hr}} Y$ if

$$\frac{P\{X = n\}}{P\{X \geq n\}} \geq \frac{P\{Y = n\}}{P\{Y \geq n\}}, \quad n \in \mathbb{N}. \quad (1.B.9)$$

Equivalently, $X \leq_{\text{hr}} Y$ if

$$\frac{P\{X = n\}}{P\{X > n\}} \geq \frac{P\{Y = n\}}{P\{Y > n\}}, \quad n \in \mathbb{N}.$$

The discrete analog of (1.B.4) is that (1.B.9) holds if, and only if,

$$P\{X \geq n_1\}P\{Y \geq n_2\} \geq P\{X \geq n_2\}P\{Y \geq n_1\} \quad \text{for all } n_1 \leq n_2. \quad (1.B.10)$$

In a similar manner (1.B.3) and (1.B.5) can be modified in the discrete case. Unless stated otherwise, we consider only random variables with absolutely continuous distribution functions in the following sections.